

DENOISING DATA WITH MULTI-ECHO EPI

(...Multi-echo EPI, Multi-echo EPI, Multi-echo EPI, Multi-echo EPI, Multi-Echo EPI, Multi-Echo EPI...)

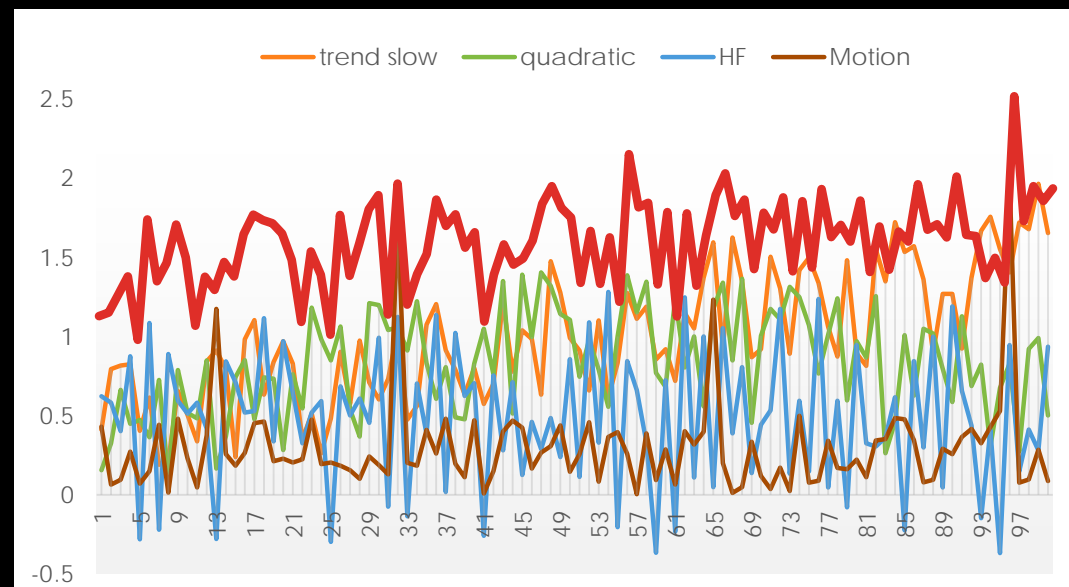
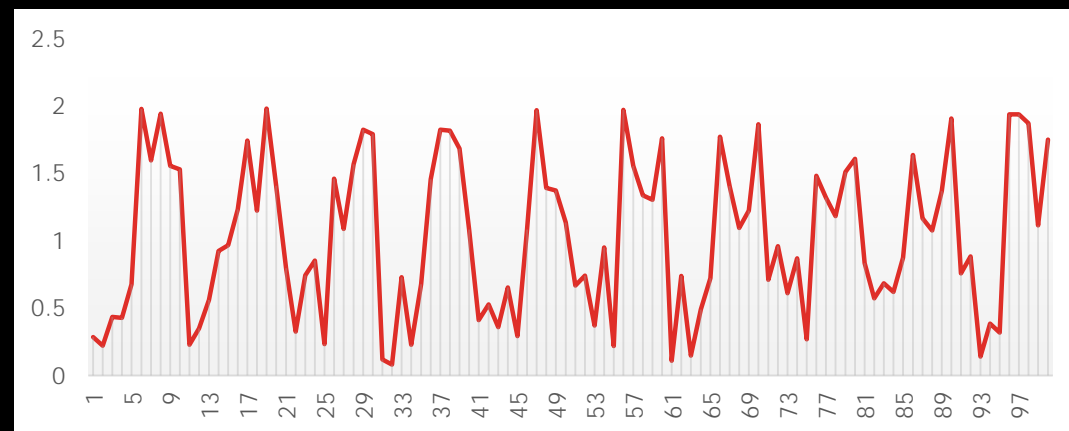
Martin M Monti, PhD

UCLA Department of Psychology

<http://montilab.psych.ucla.edu>

THE PROBLEM

"[...] data from standard (i.e. single-echo) fMRI pulse sequences is limited by the fundamental problem that in such experiments, Blood Oxygen Level Dependent (BOLD) signal arising from spontaneous neuronal activity is not differentiable from fluctuations arising from cardiac and respiratory physiology, motion, and many other sources."
Kundu et al., 2012

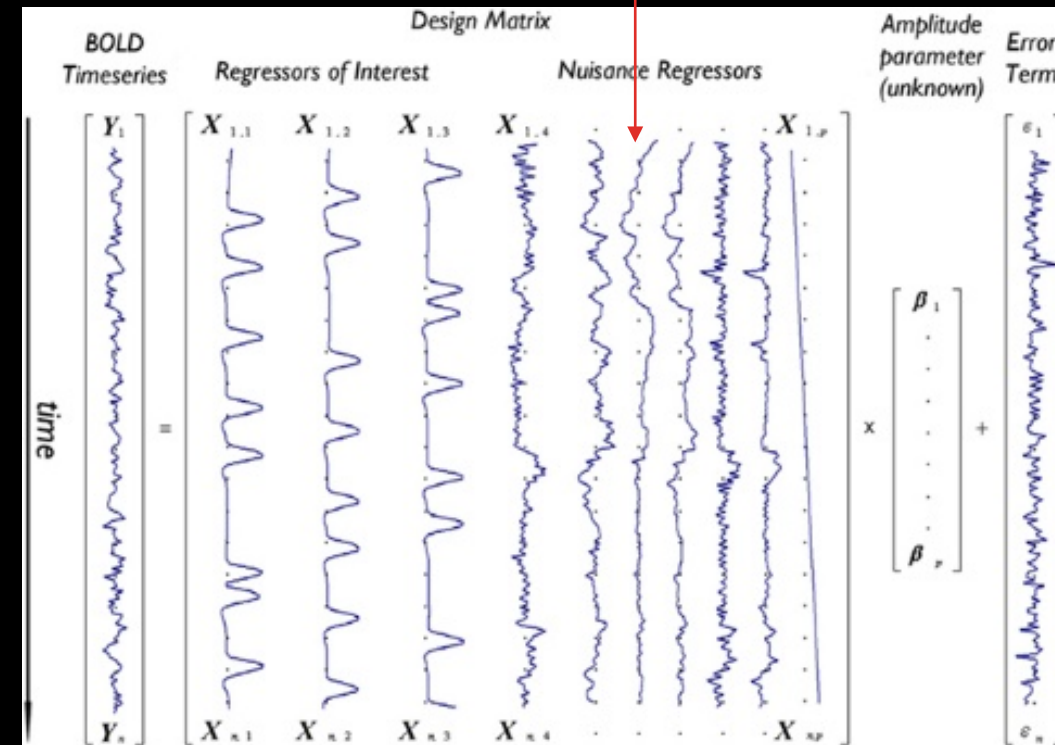
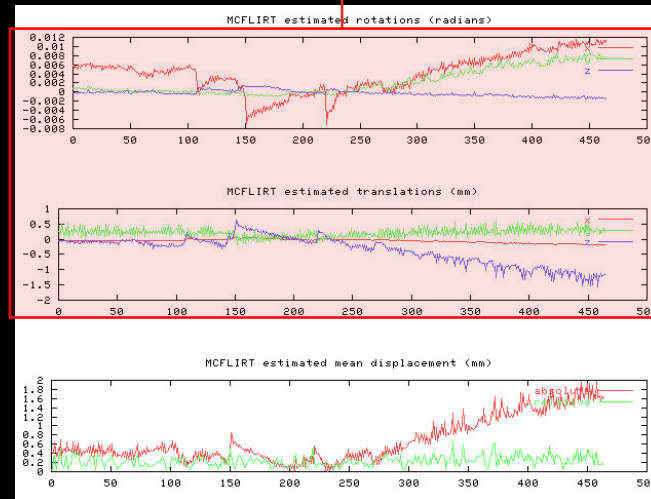


THE PROBLEM

- Task-based fMRI (GLM-based analysis):
 - a-priori hypothesis of the signal of interest. If noise is correlated with the task-related activity it can produce false activations/deactivations/etc.
- Resting state fMRI:
 - NO a-priori hypothesis about the signal of interest: any correlation with noise will produce false positives

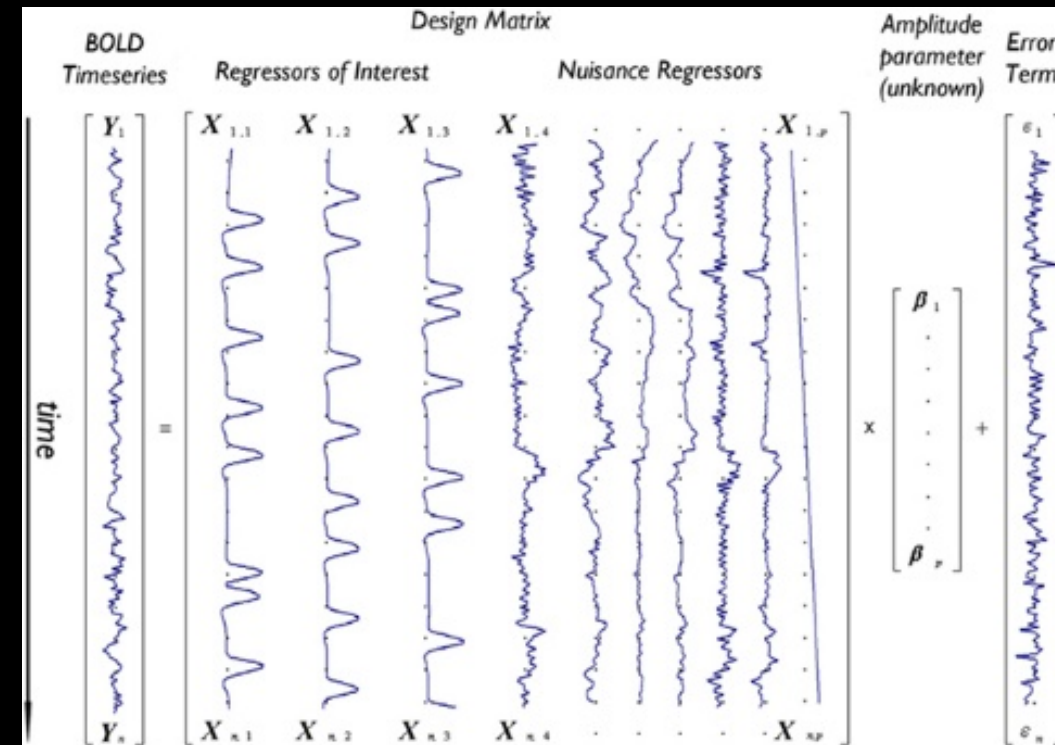
APPROACH #1: THE STANDARD

- Motion correction



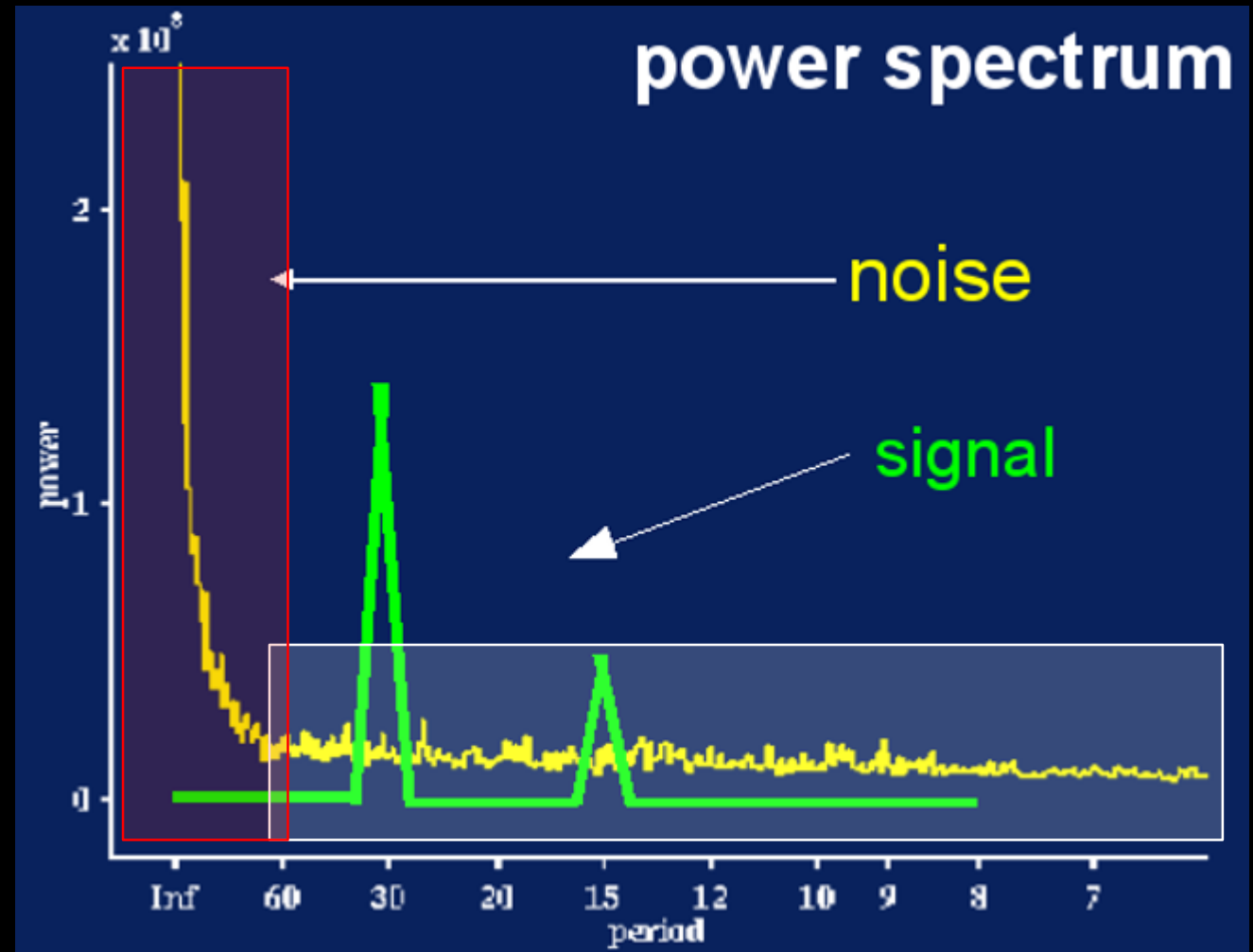
APPROACH #1: THE STANDARD

- Motion correction
 - But residual motion, intra-TR motion, spin history effects remain
- Outliers/Scrubbing (Power et al., 2012)
 - Might lose a lot of data
- Global Mean Signal regression
 - Anti-correlations issue (Murphy et al., 2009)
- WM/CSF Regression
 - Doesn't do that much (Power et al., 2012)
- Physiological recording (Glover et al., 2000)



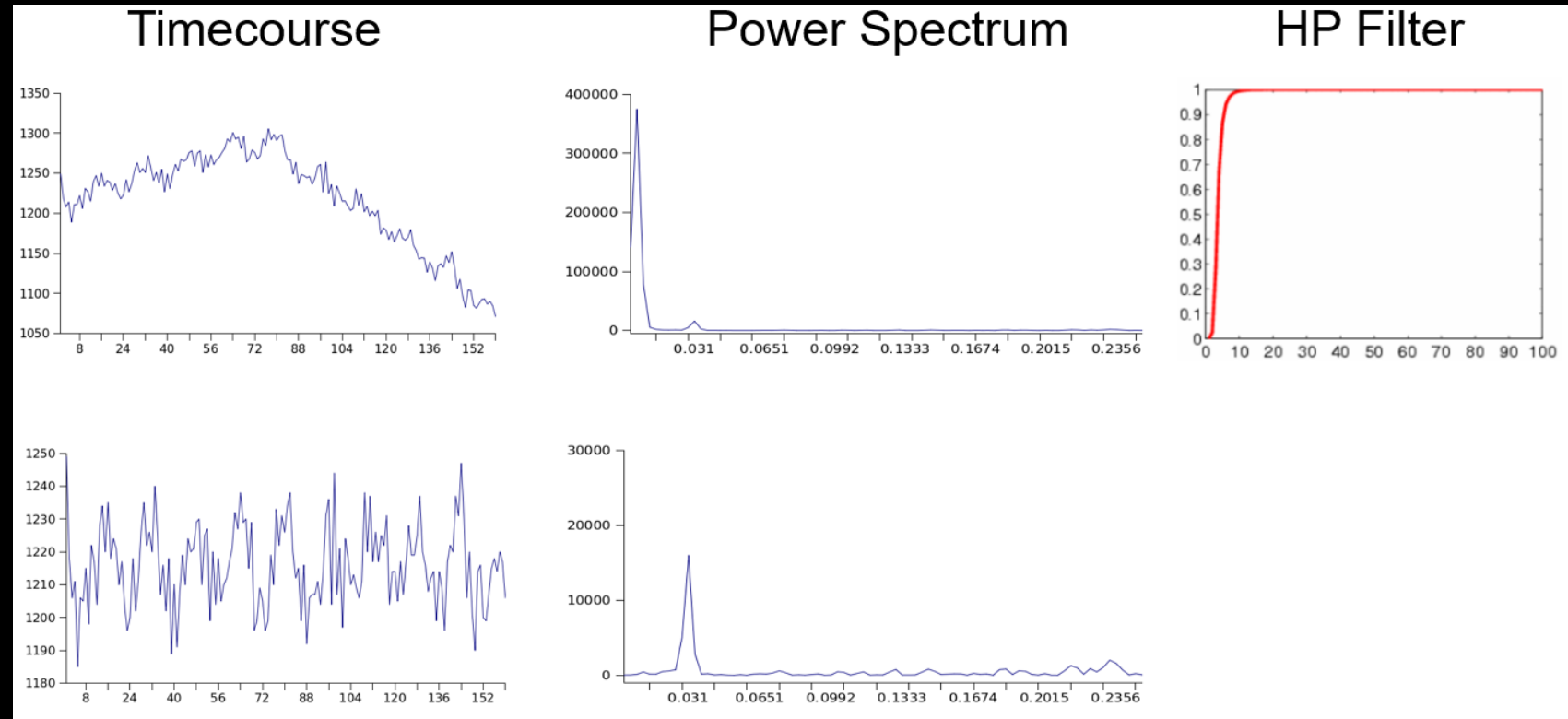
APPROACH #1: THE STANDARD

- Spatial filtering



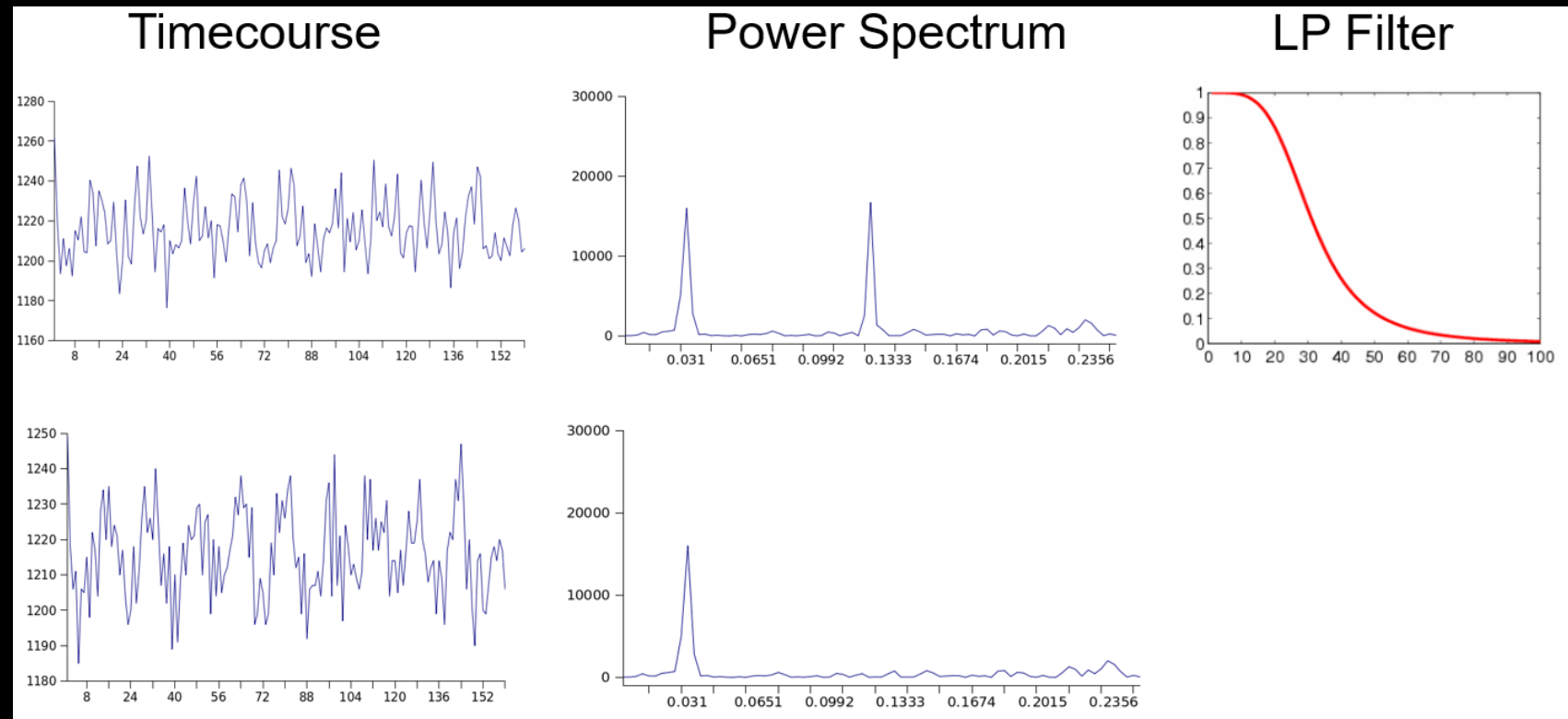
APPROACH #1: THE STANDARD

- Motion correction
- Spatial filtering
 - Low Freq Noise



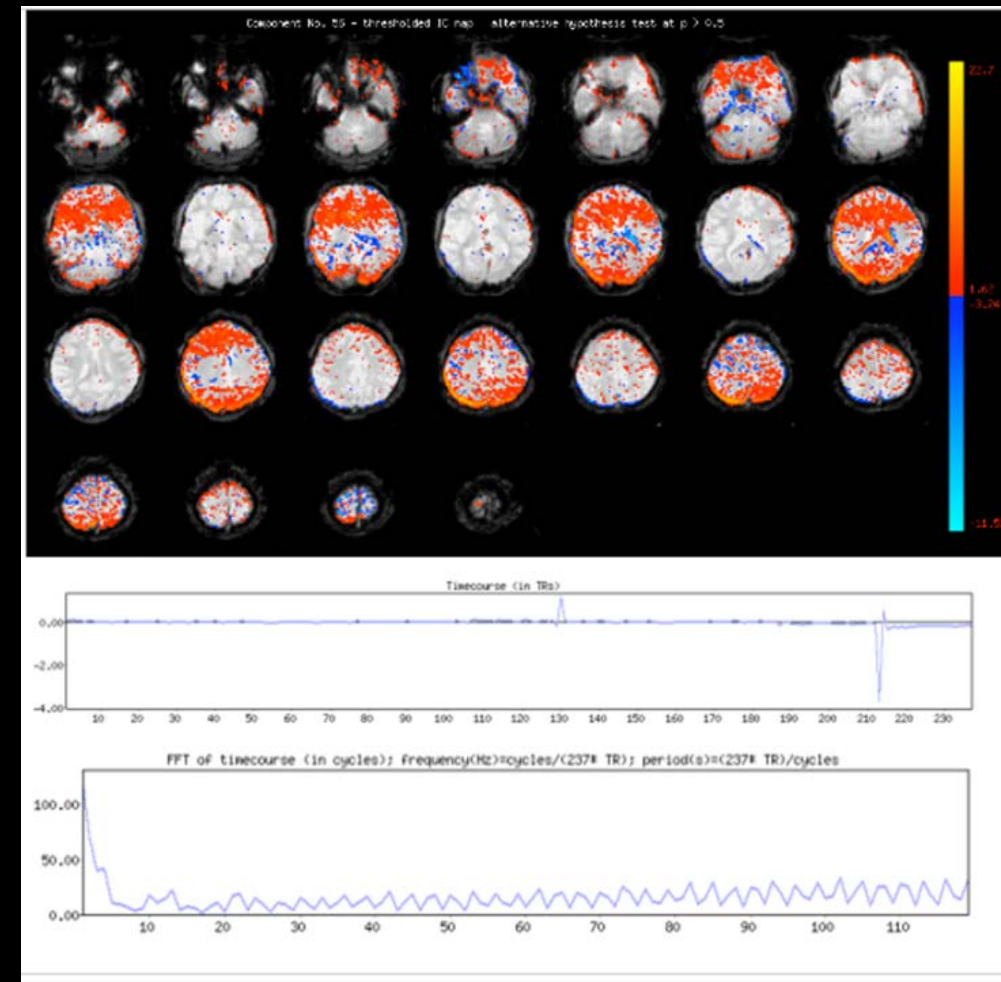
APPROACH #1: THE STANDARD

- Motion correction
- Spatial filtering
 - Low Freq Noise
 - High Freq Noise



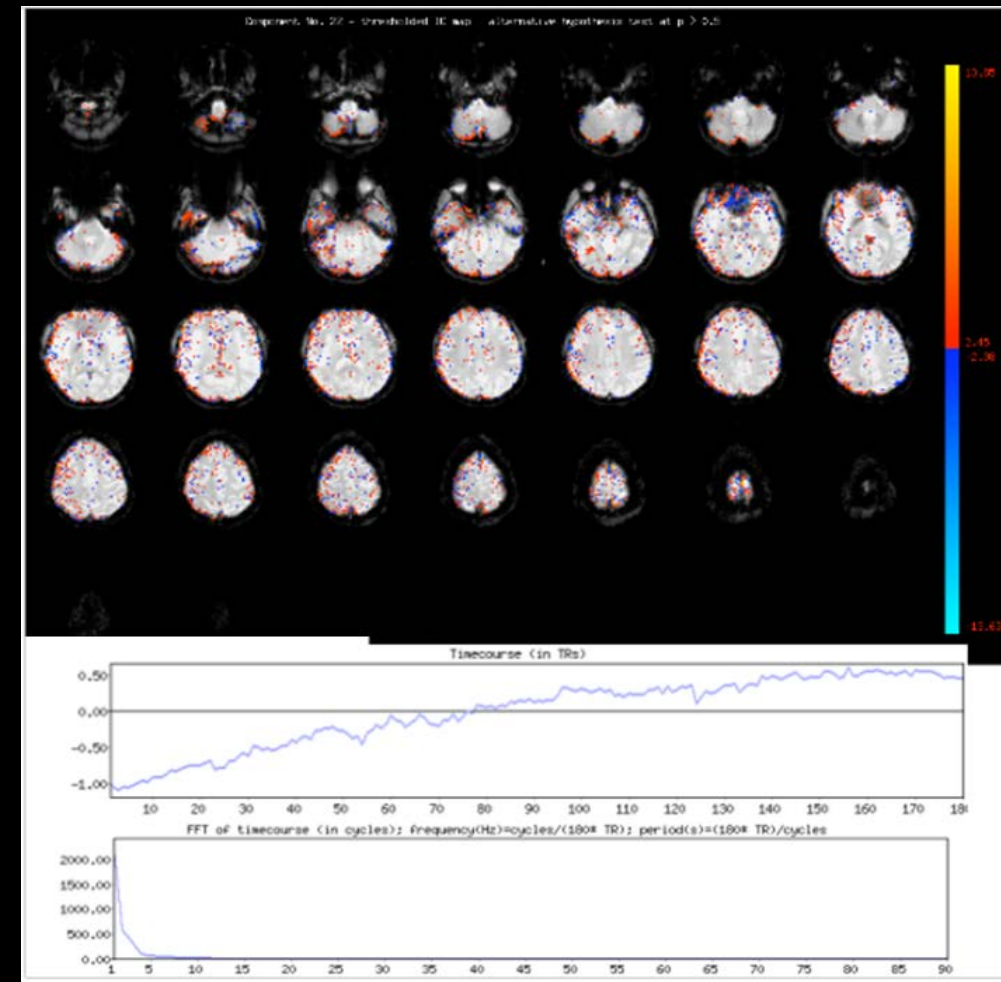
APPROACH #2: DATA DRIVEN STRUCTURED NOISE REMOVAL

- Use data driven method to find noise and remove it from the data
 - Still have to run standard preprocessing including motion correction, high-pass filtering
- Identify bad components
 - Subjective (if done manually)
- Remove bad components from signal



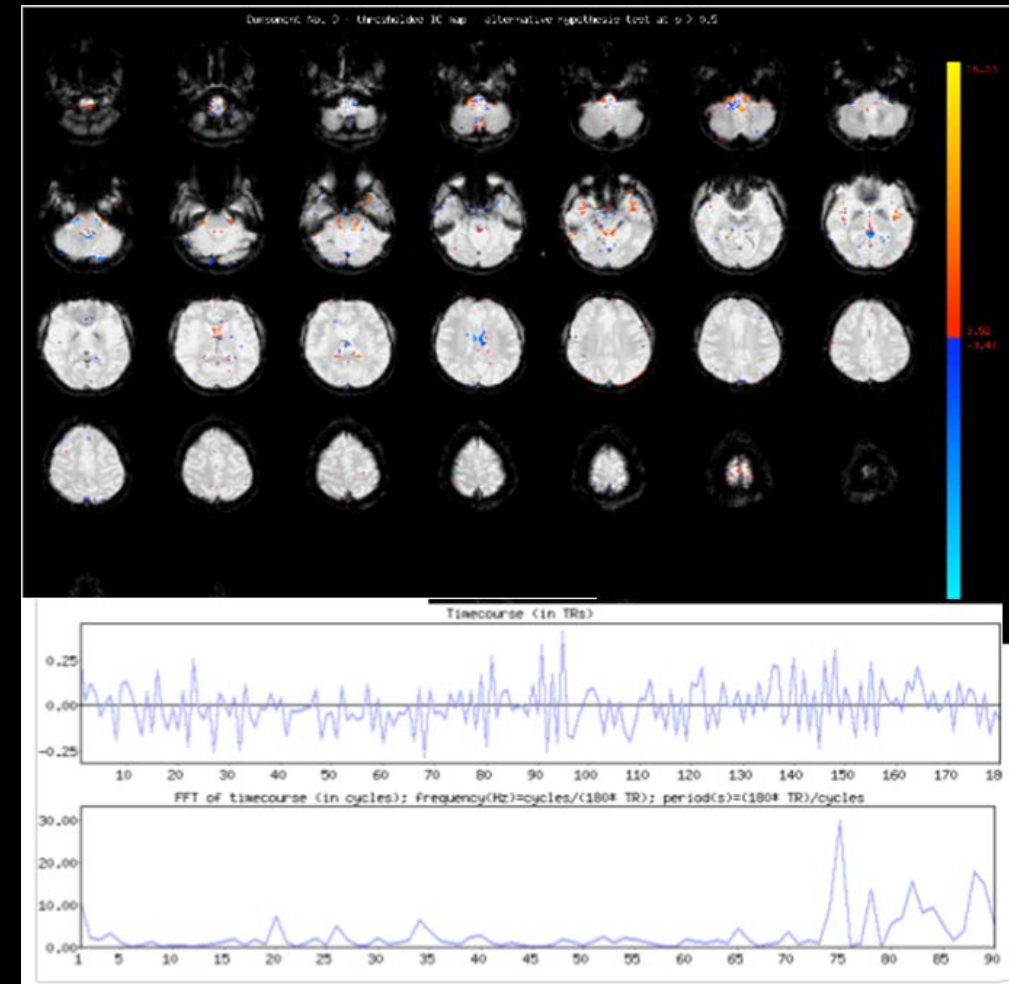
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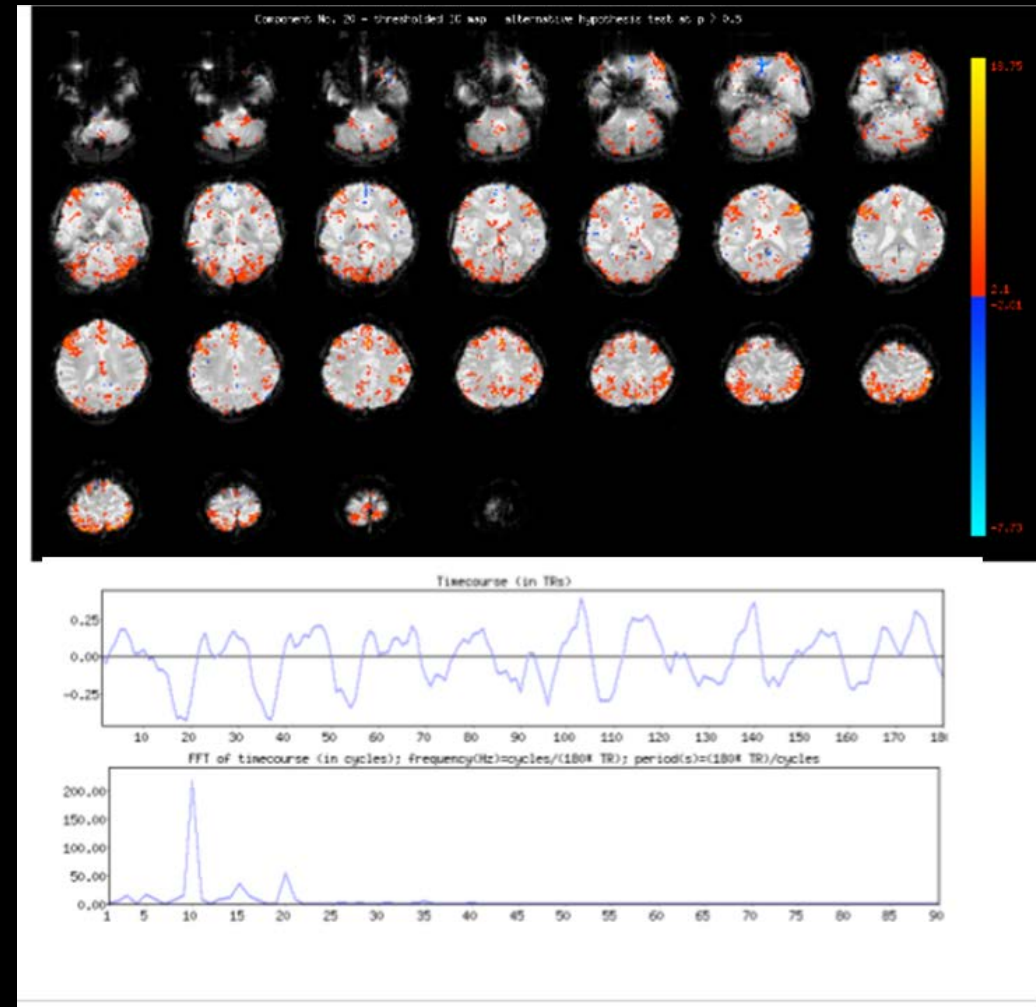
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APPROACH #2: DATA DRIVEN STRUCTURED NOISE REMOVAL

- Use data driven method to find noise and remove it from the data
 - Still have to run standard preprocessing including motion correction, high-pass filtering
- Identify bad components
 - Subjective (if done manually)
- Remove bad components from signal
- Today, automated tools exist (FIX)



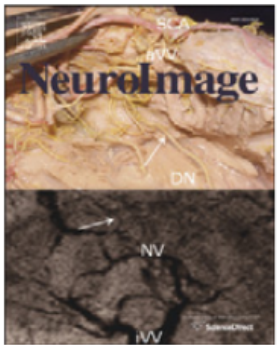
APPROACH #3: MULTI-ECHO EPI



Contents lists available at [SciVerse ScienceDirect](#)

NeuroImage

journal homepage: www.elsevier.com/locate/ynimg



Differentiating BOLD and non-BOLD signals in fMRI time series using multi-echo EPI

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^b Functional MRI Facility, National Institute of Mental Health, National Institutes of Health, Bethesda, MD, 20892 USA

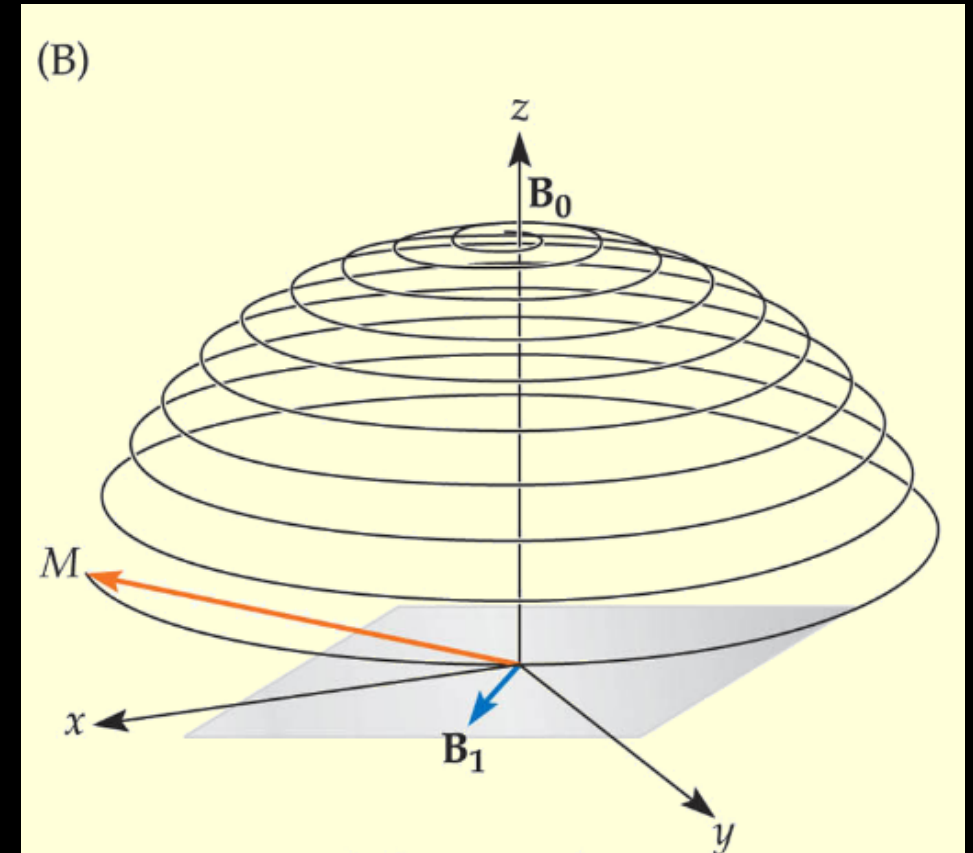
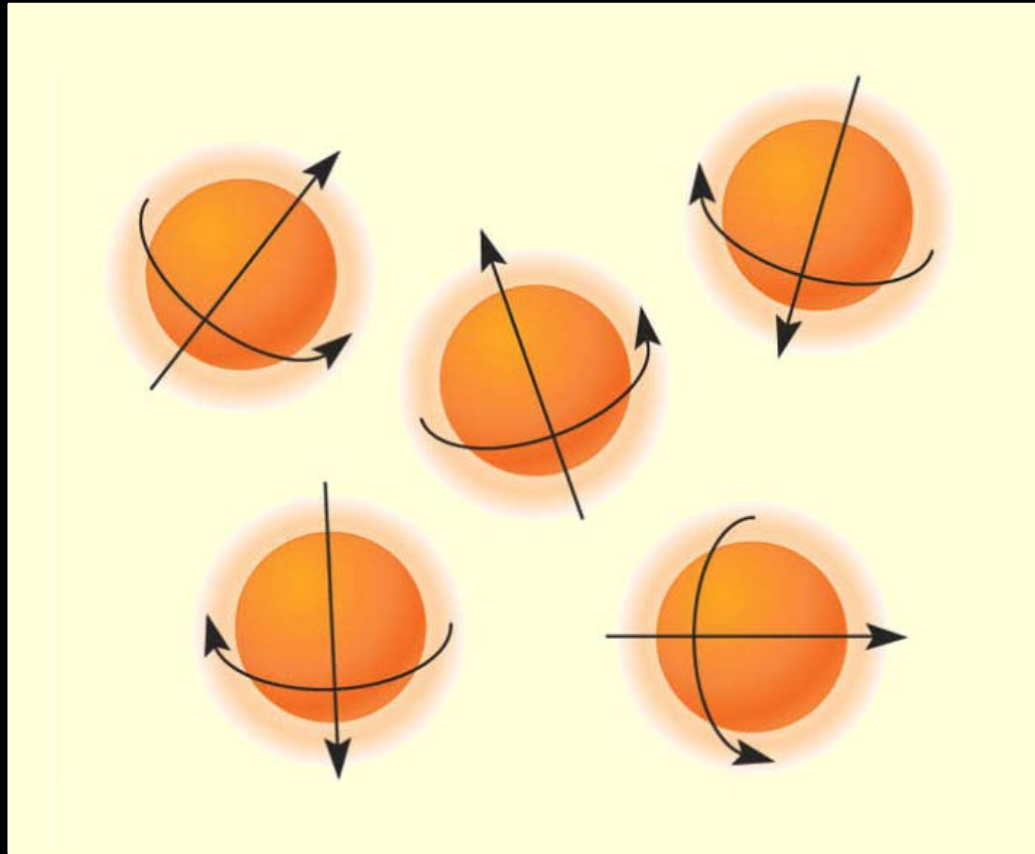
^c Department of Psychiatry, University of Cambridge, Addenbrooke's Hospital, Hills Road, Cambridge, CB2 2QQ UK

^d Center for Neuroscience and Regenerative Medicine, Henry M. Jackson Foundation, Rockville, Maryland, 20852 USA

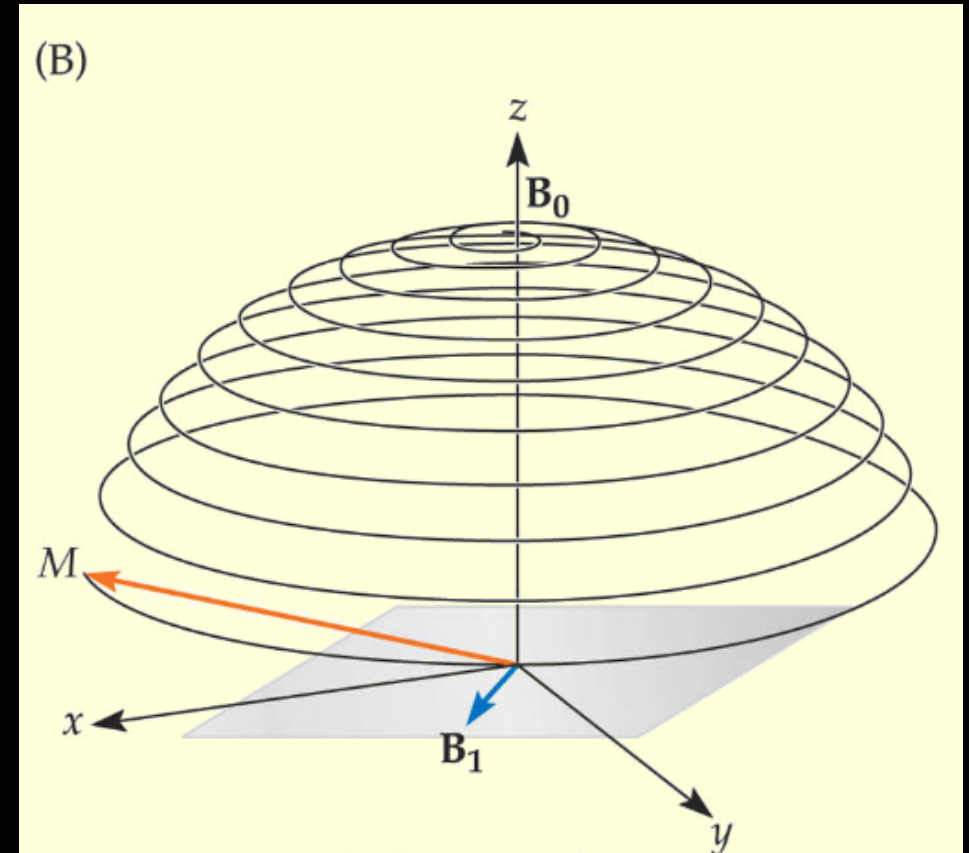
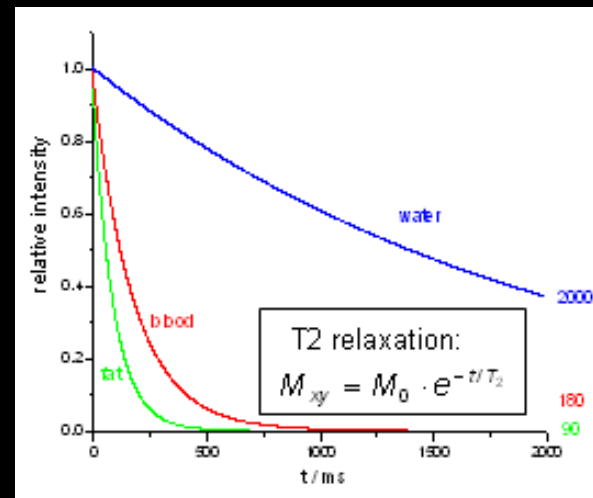
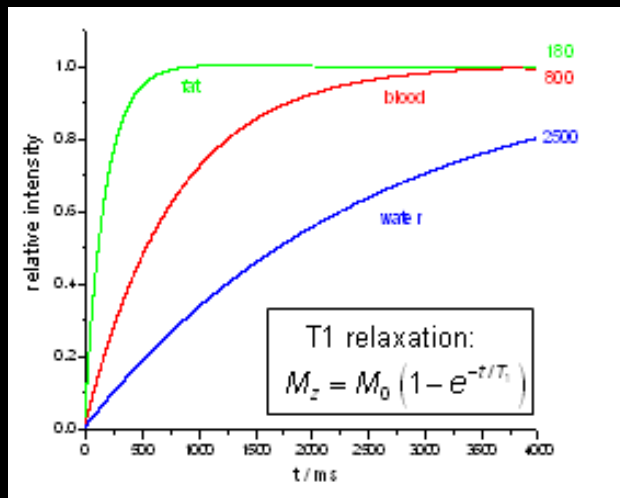
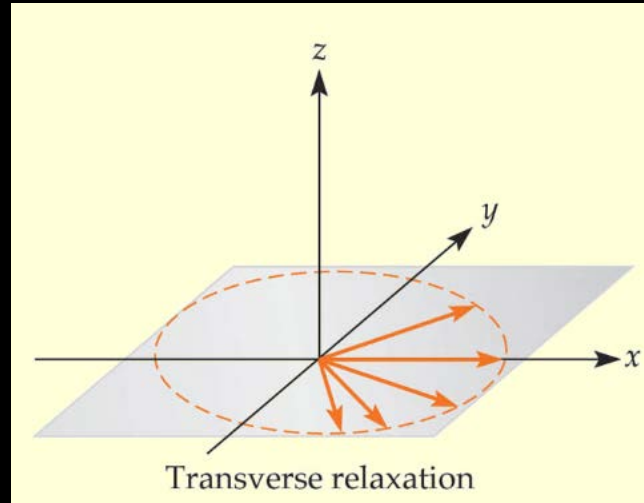
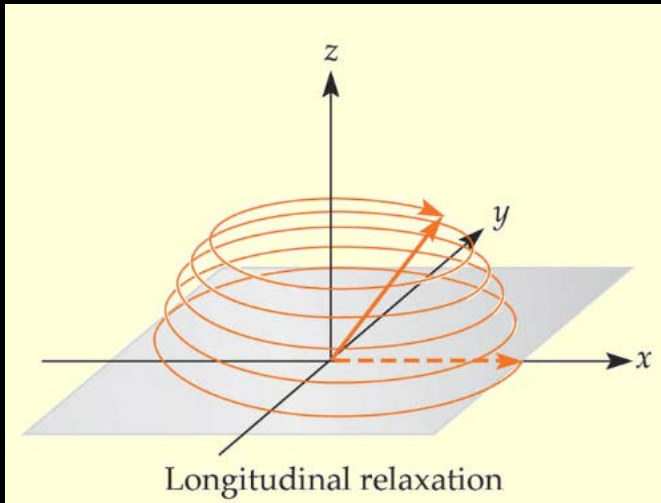
APPROACH #3: MULTI-ECHO EPI

- “We introduce a new method that employs multi-echo acquisition and a TE-dependence test to remove artefactual fluctuations more effectively than these previous approaches by cleanly separating BOLD and non-BOLD signal components of resting state data.” Kundu et al., 2012

BACK TO BASICS

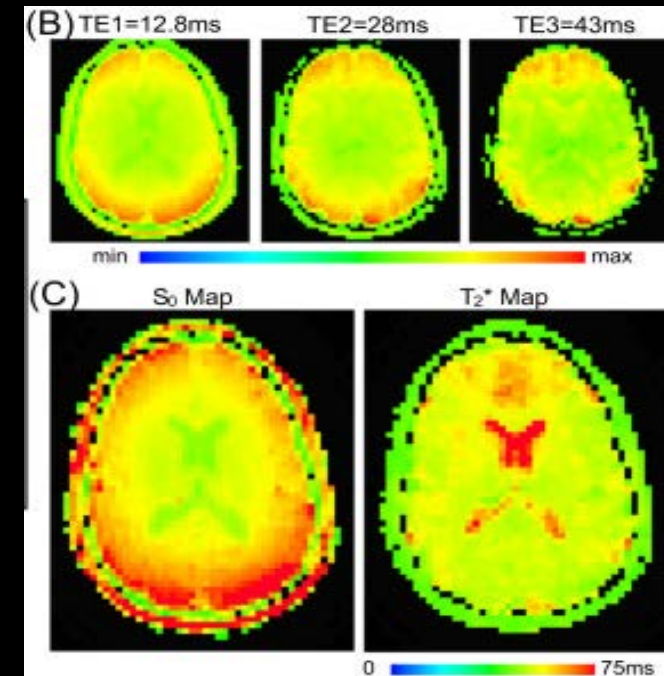
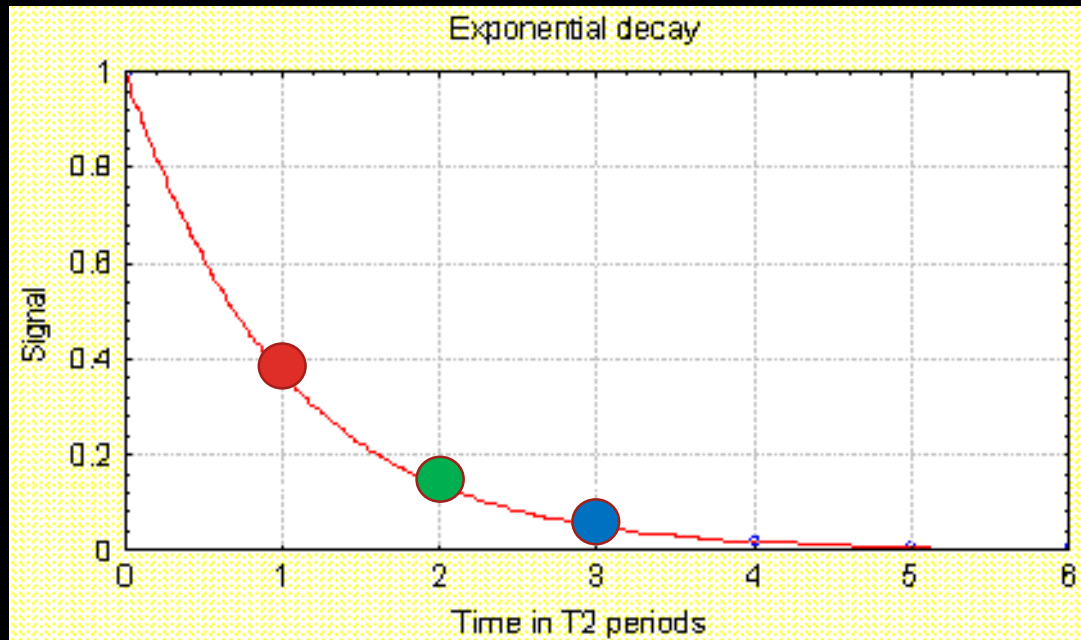


BACK TO BASICS



APPROACH #3: MULTI-ECHO EPI

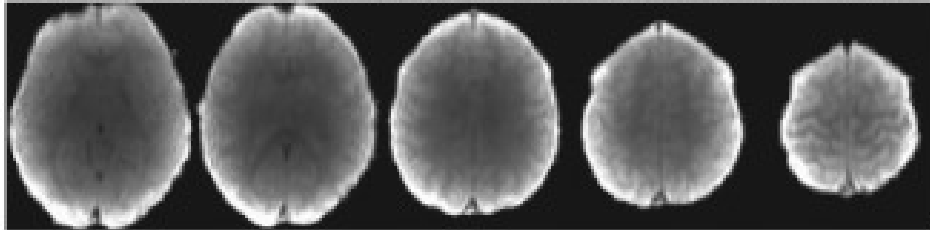
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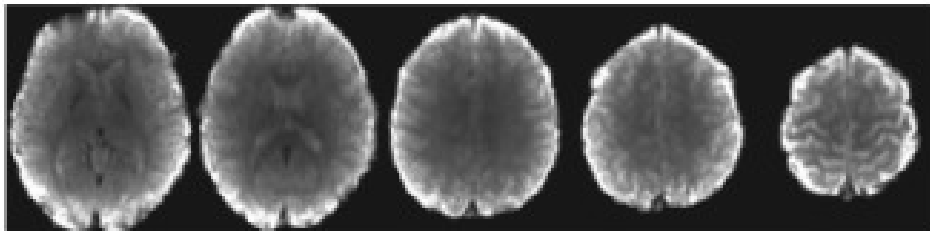
APPROACH #3: MULTI-ECHO EPI

(A) 3T Multi-echo EPI (2.5mm iso., TR=0.98s, GRAPPA 2, MB=4)

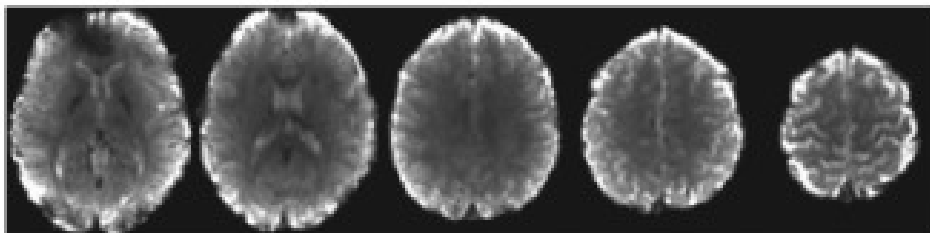
TE=15ms



TE=31ms

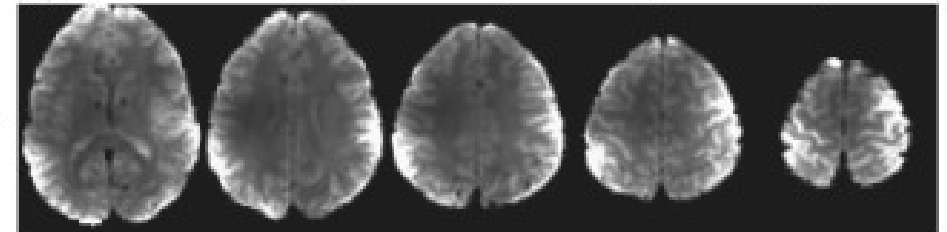


TE=48ms

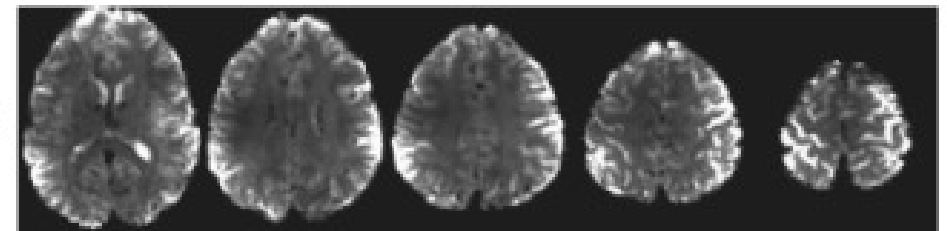


(B) 7T Multi-echo EPI (2.5mm iso., TR=1.8s, GRAPPA 3, MB=2)

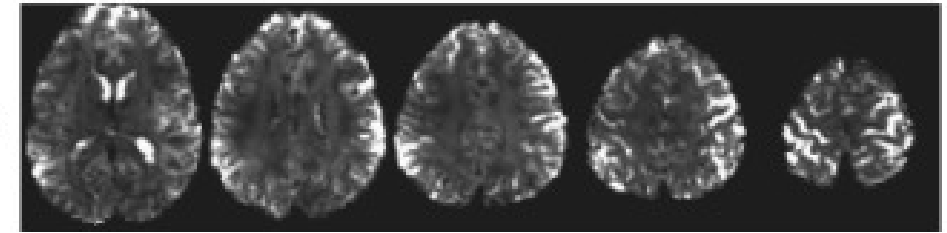
TE=8ms



TE=23ms

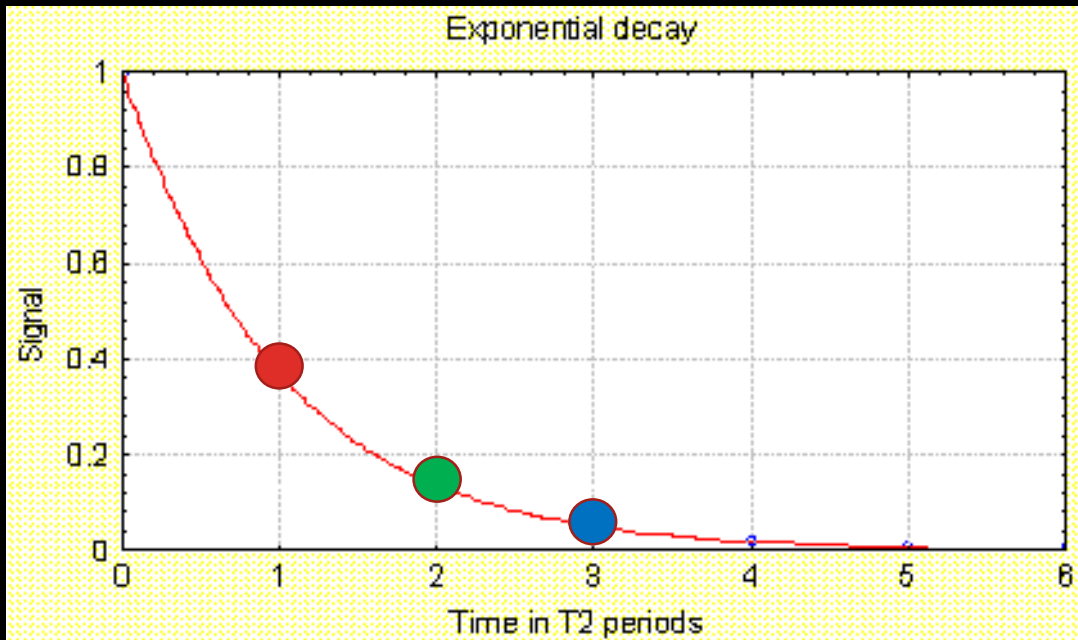


TE=37ms

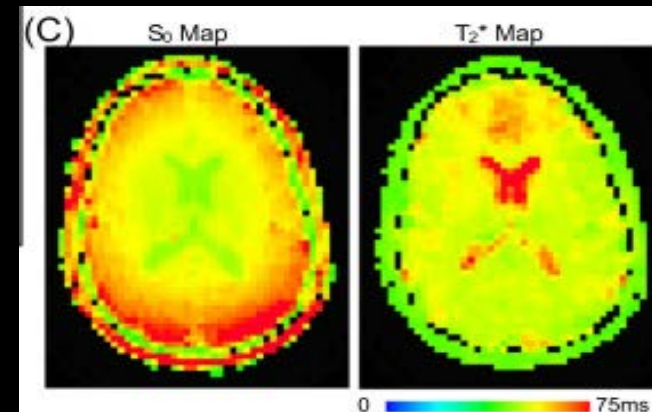


APPROACH #3: MULTI-ECHO EPI

- “We introduce a new method that employs multi-echo acquisition and a TE-dependence test to remove artefactual fluctuations more effectively than these previous approaches by cleanly separating BOLD and non-BOLD signal components of resting state data.” Kundu et al., 2012

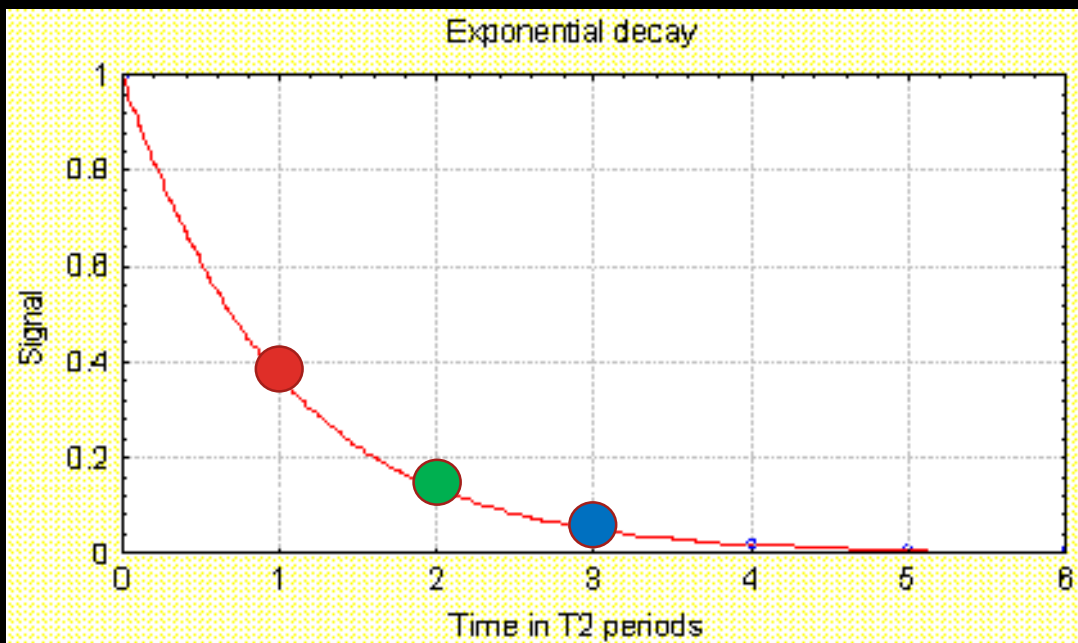


$$S(TE_n) = S_0 \exp(-R_2^* TE_n)$$



APPROACH #3: MULTI-ECHO EPI

- “We introduce a new method that employs multi-echo acquisition and a TE-dependence test to remove artefactual fluctuations more effectively than these previous approaches by cleanly separating BOLD and non-BOLD signal components of resting state data.” Kundu et al., 2012



$$S(TE_n) = S_0 \exp(-R_2 * TE_n)$$

$$\Delta S/S = \Delta S_0/S_0 + \Delta R_2 * TE$$

NON-BOLD model

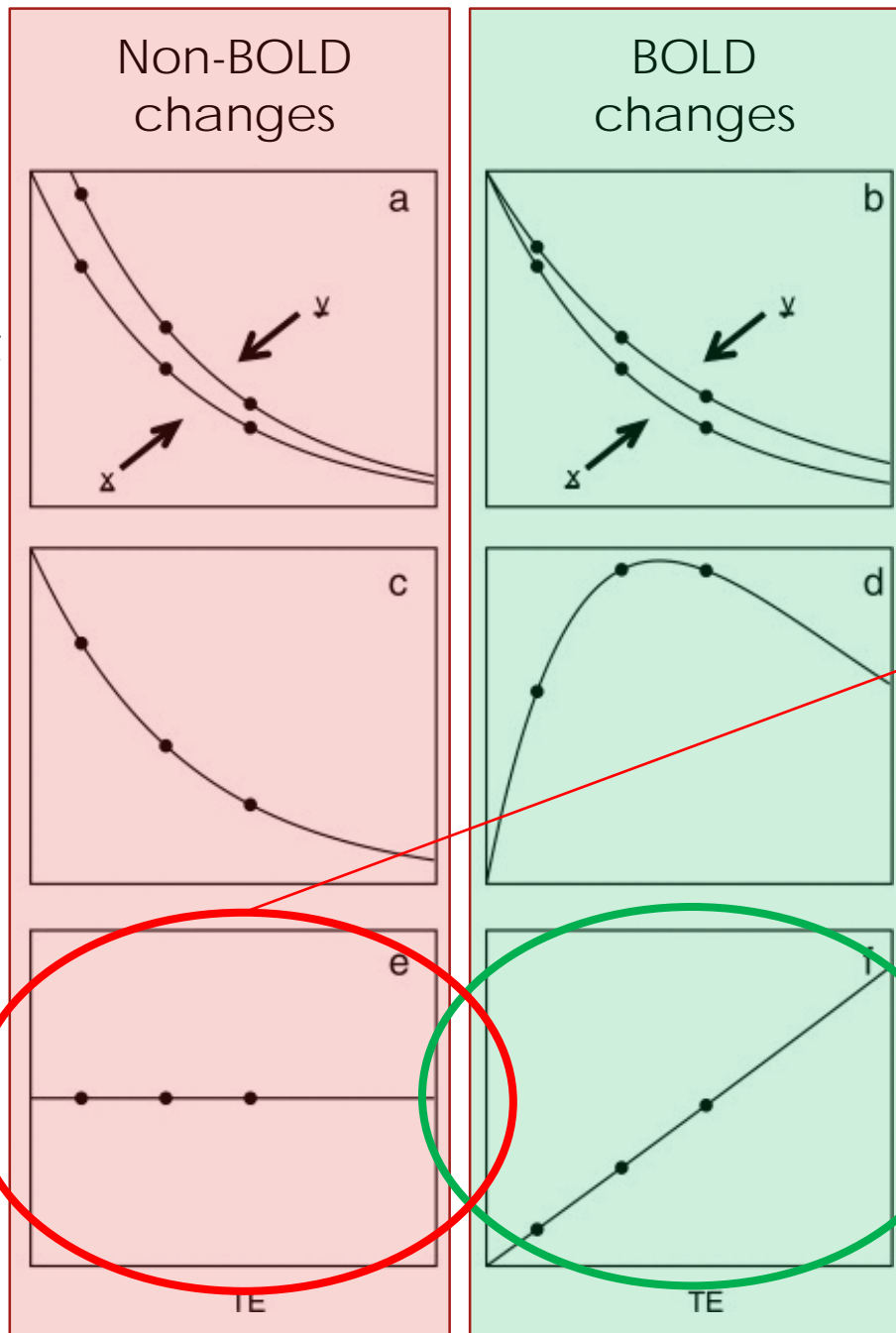
$$\Delta S/S = \Delta S_0/S_0$$

BOLD model

$$\Delta S/S = -\Delta R_2 * TE$$

KUNDU ET AL 2012

Task & Rest



Task - Rest

% Signal Change

If a signal fits this model
(goodness of fit F), then it's not
of BOLD origin!

$$\Delta S/S = \Delta S_0/S_0 \quad (\rho)$$

Good signals have
to fit this model
(goodness of fit F)!

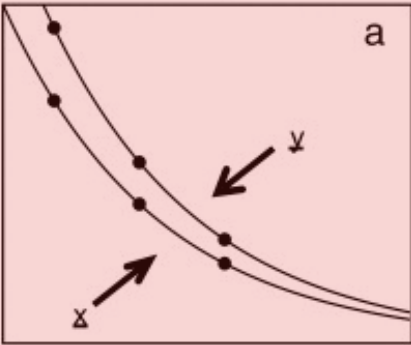
$$\Delta S/S = -\Delta R_2 * TE \quad (\kappa)$$

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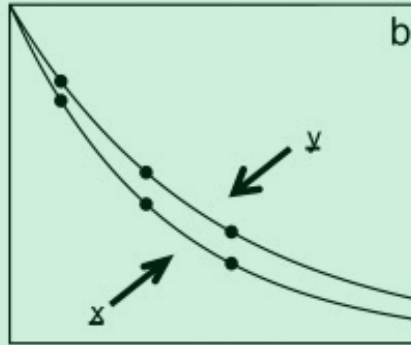
The key idea is that, when expressed in terms of ***percent signal change***, we know how the BOLD signal should behave as TE increases.

Task & Rest

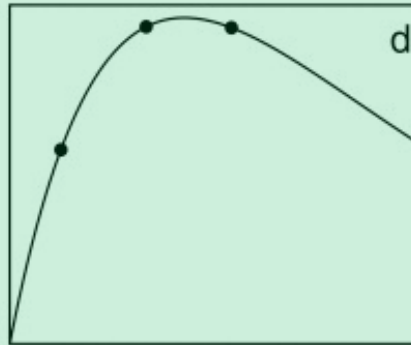
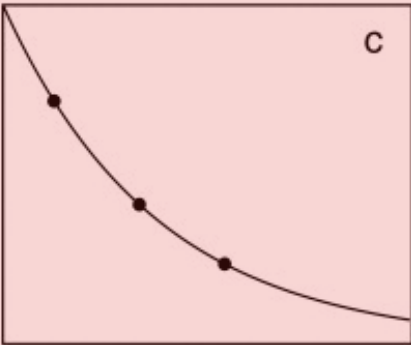
Non-BOLD changes



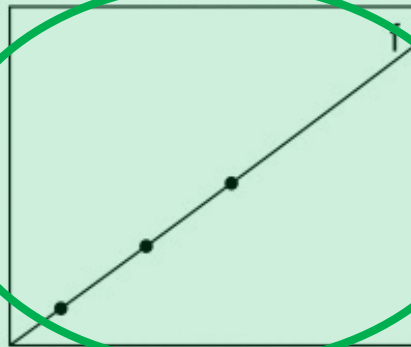
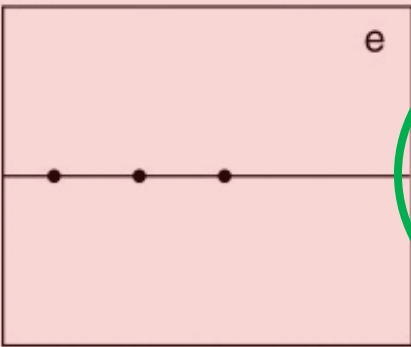
BOLD changes



Task - Rest



% Signal Change

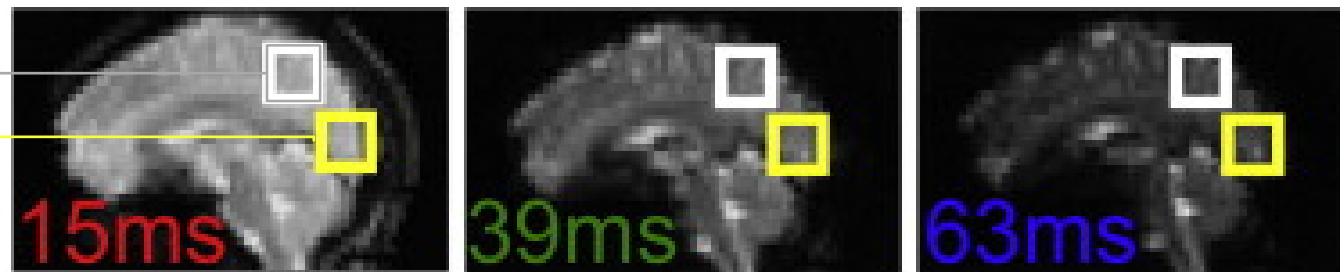


TE

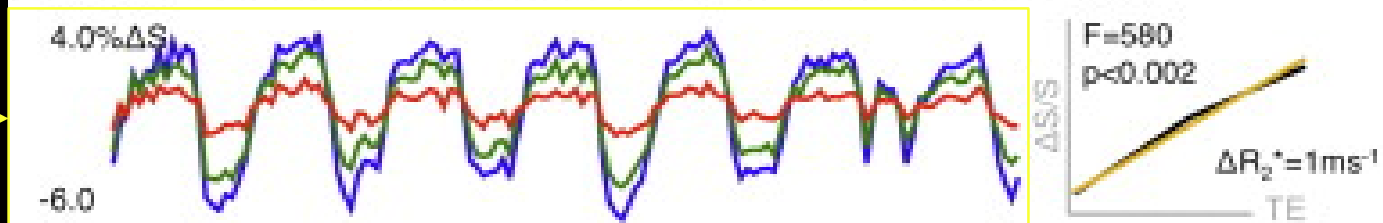
TE

KUNDU ET AL 2012

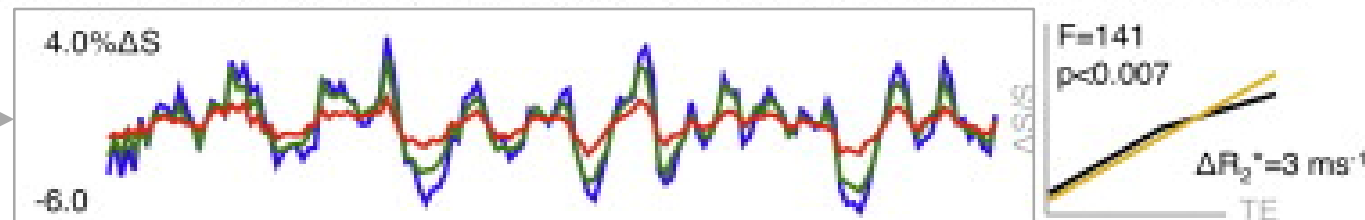
a Multi-echo EPI images

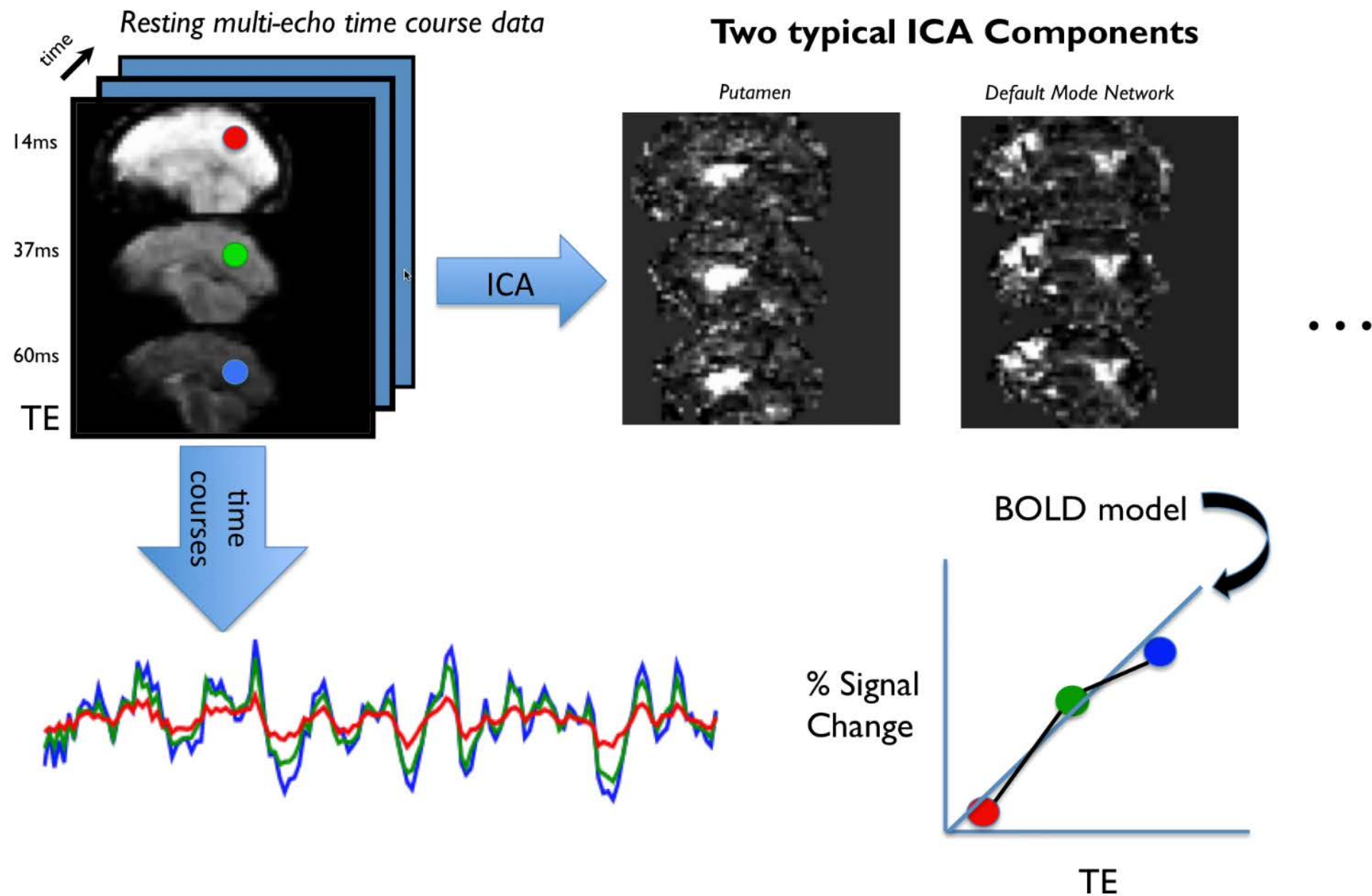


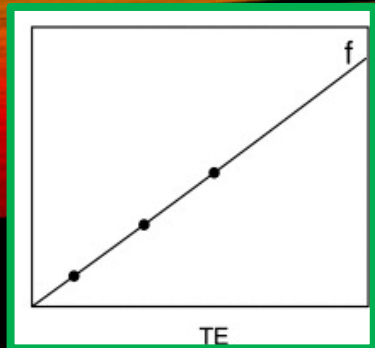
b Multi-echo EPI time courses for task (V1)



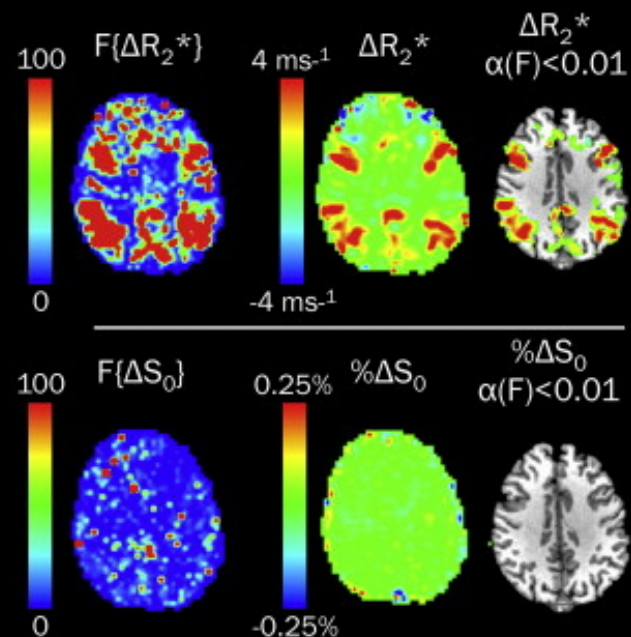
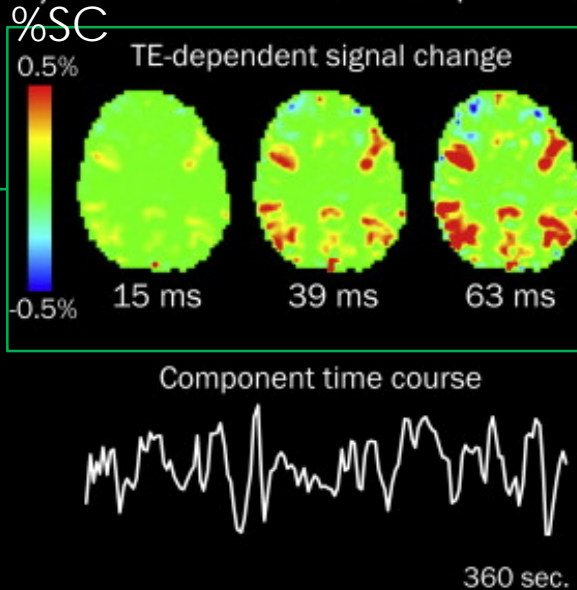
c Multi-echo EPI time courses for rest (precuneus)



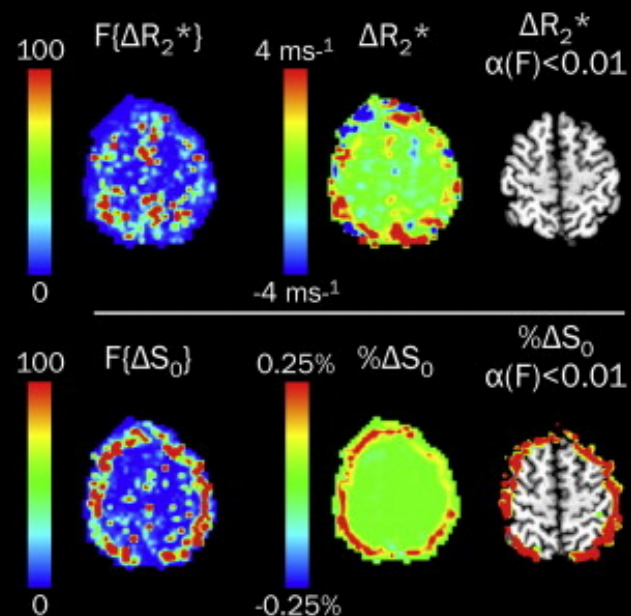
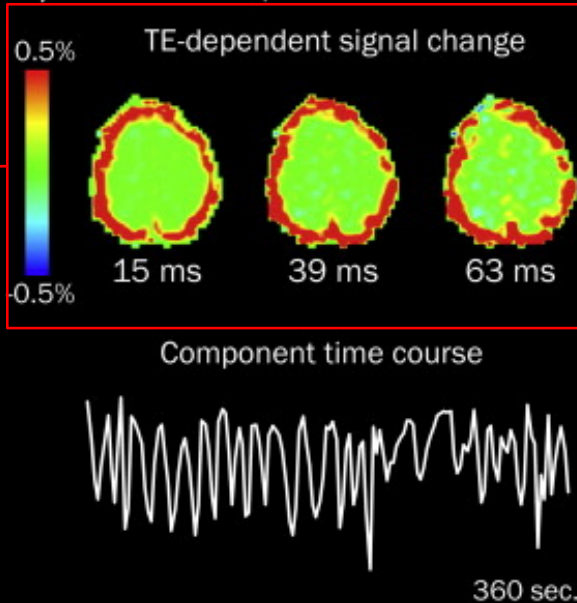




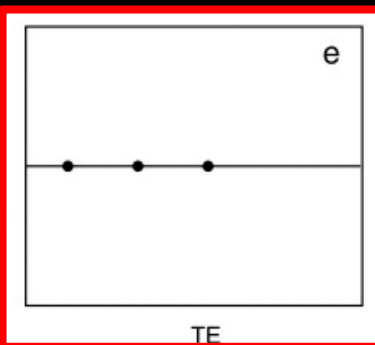
a) Functional Network Component



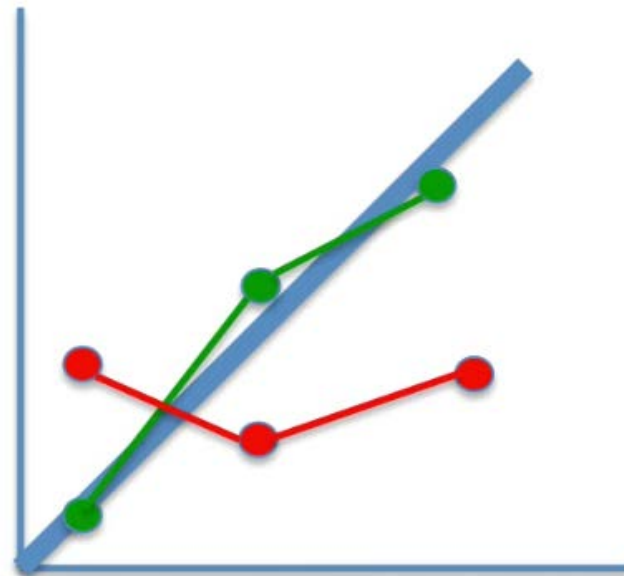
b) Artifact Component



RESULTS



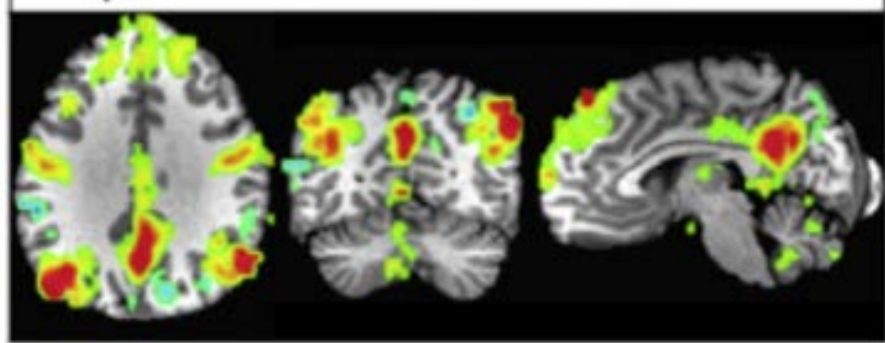
% Signal
Change



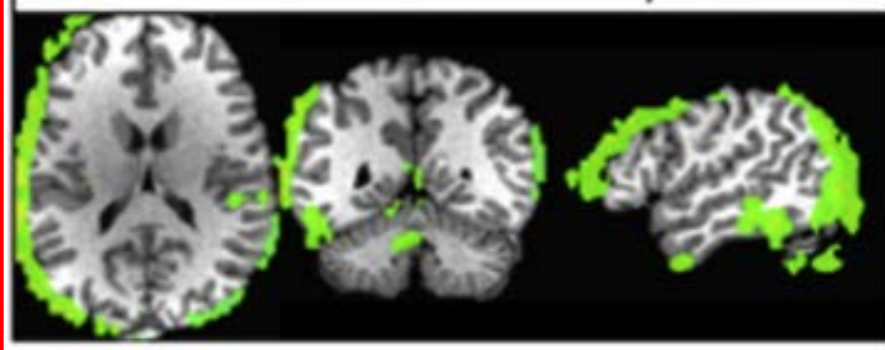
TE

RESULTS

$\kappa=117$ $\rho=16$ IC6

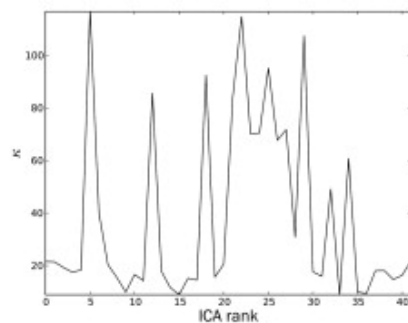


$\kappa=18$ $\rho=63$ IC4

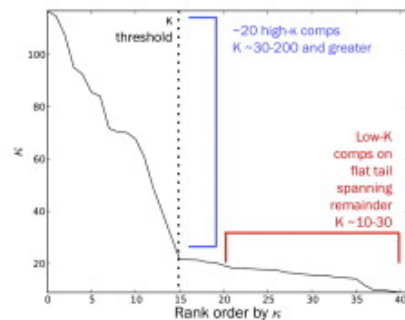


RESULTS

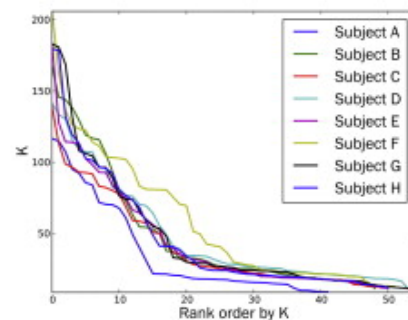
a κ vs. ICA rank



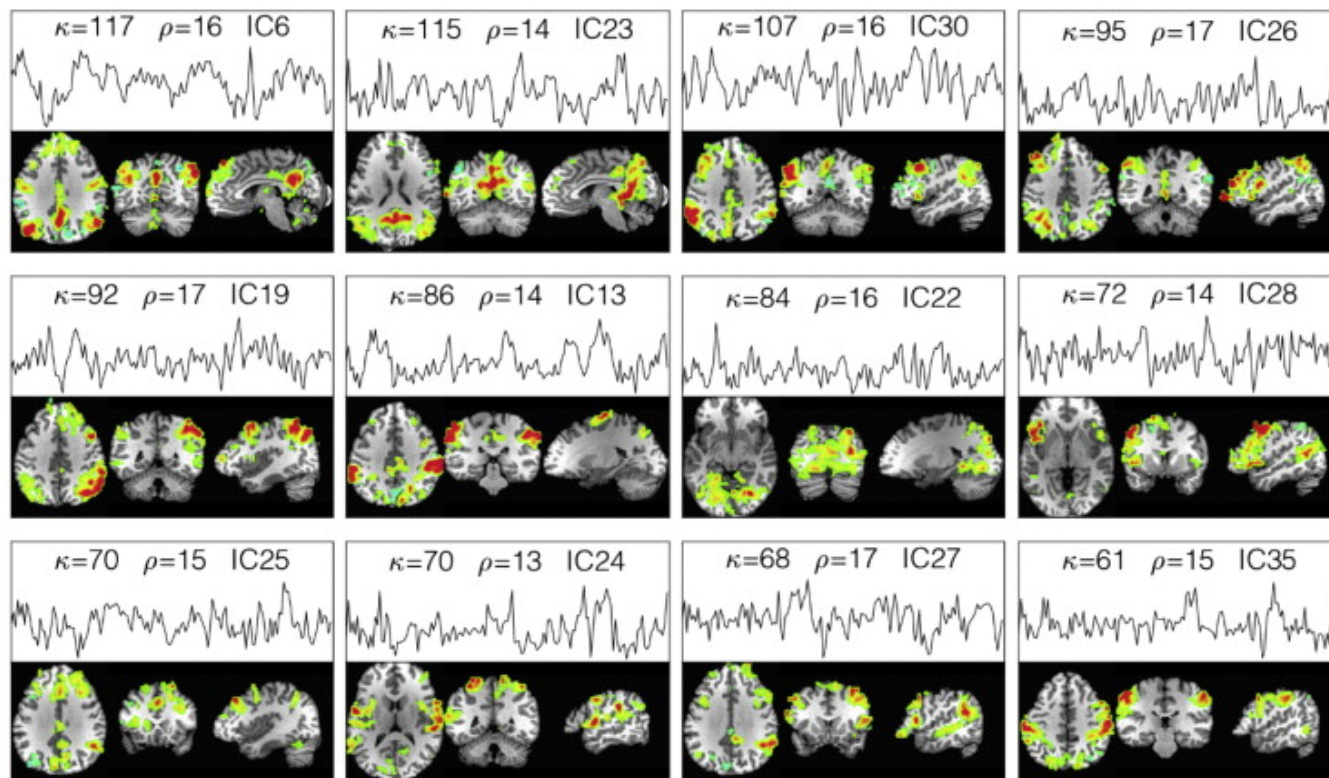
b κ spectrum



c κ spectra across subjects



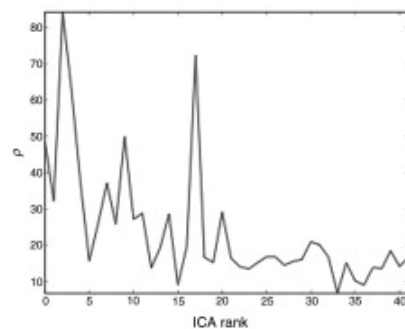
d ΔR_2^* maps of top κ ranked components for a representative subject



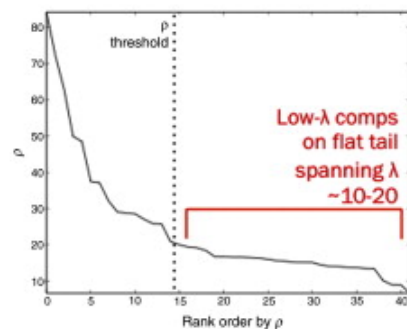
$p(F_{\Delta R_2^*}) < 0.05$ $\alpha(F_{\Delta R_2^*}) < 0.01$ | ΔR_2^* : -4 ms⁻¹ 4 ms⁻¹

RESULTS

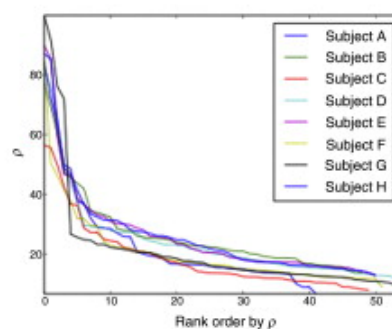
a ρ vs. ICA rank



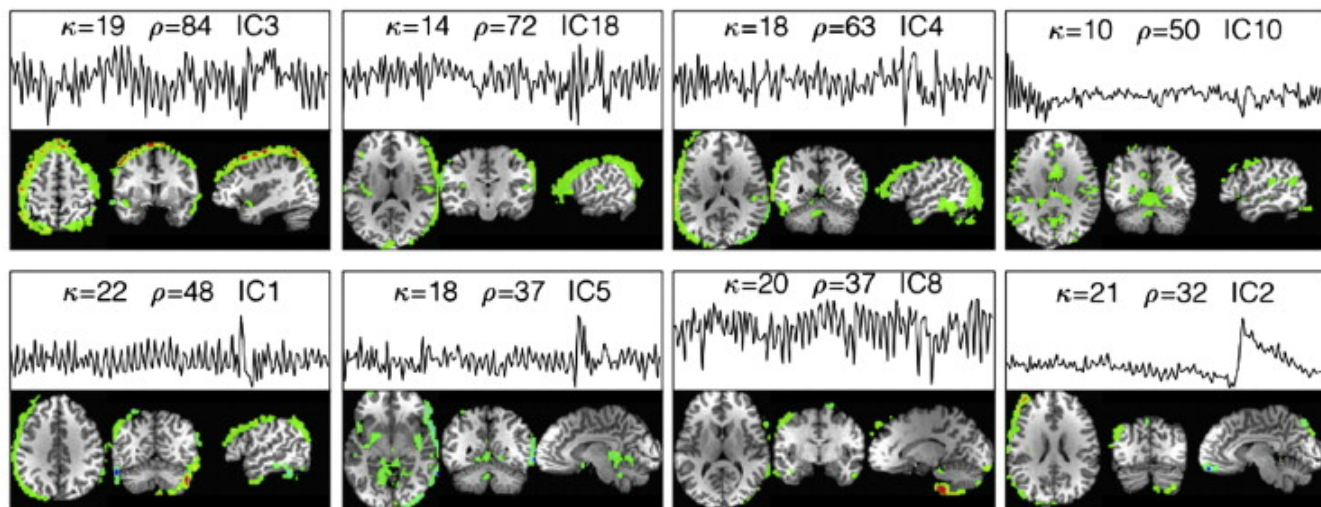
b ρ -spectrum



c ρ -spectrum across subjects

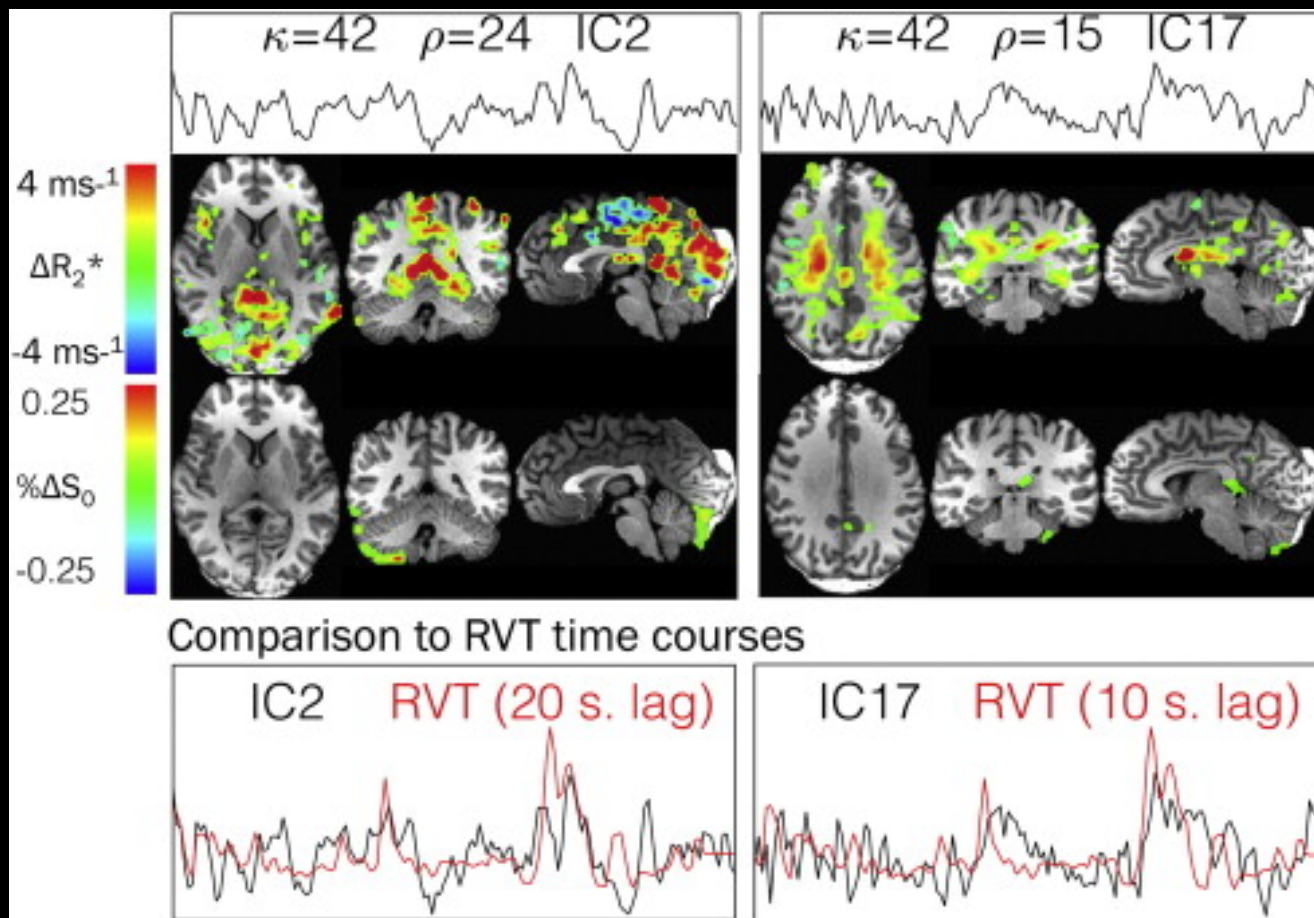


d ΔS_0 maps of top ρ -ranked components for a representative subject



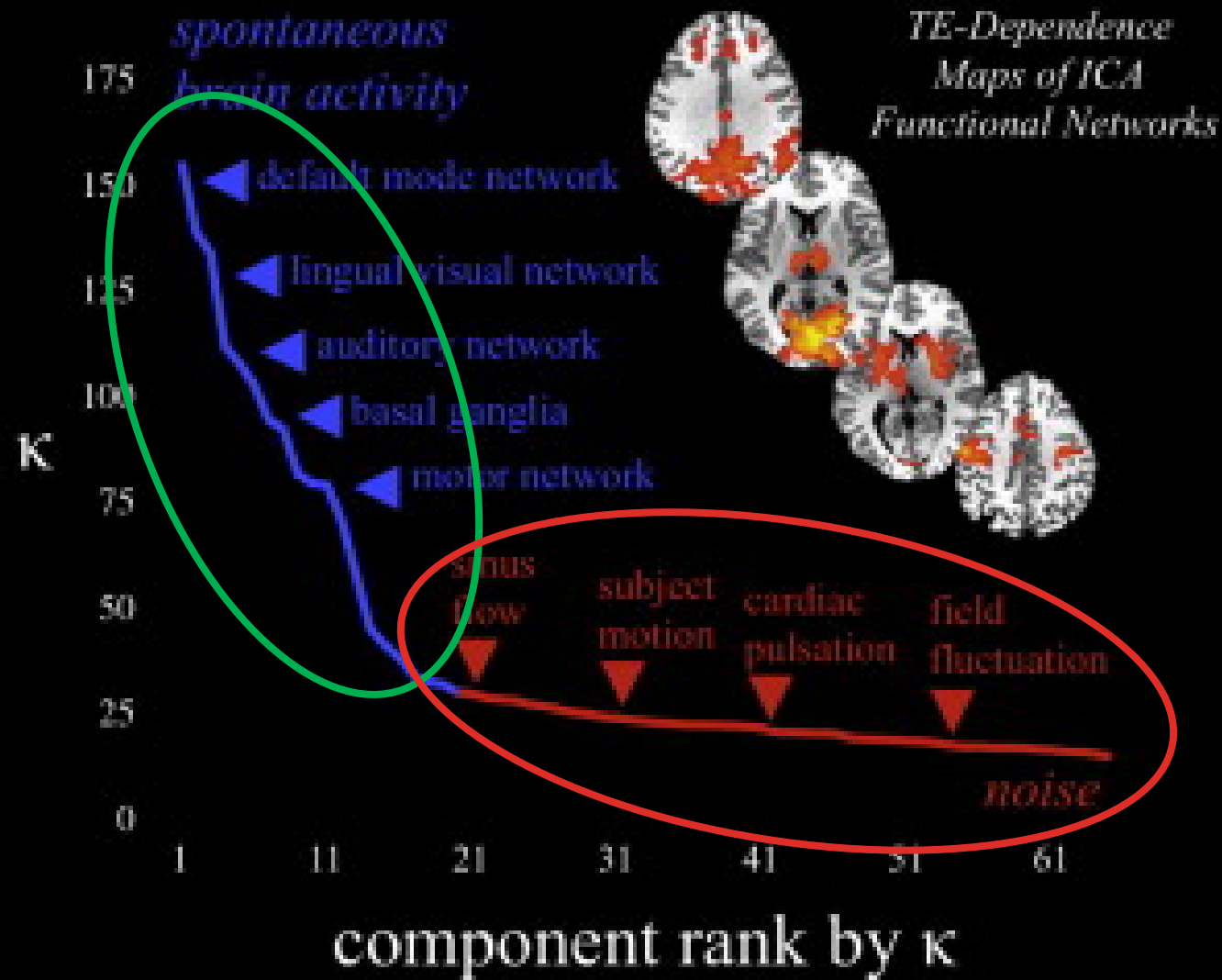
$p(F_\rho) < 0.05$ $\alpha(F_\rho) < 0.01$ $|\% \Delta \rho|$: -0.25% 0.25%

RESULTS



- What happens nearby the κ elbow?
- A component with a near-threshold κ score **could reflect** ΔR_2^* modulation from respiratory variation or related BOLD-like effects of no interest.

κ spectrum



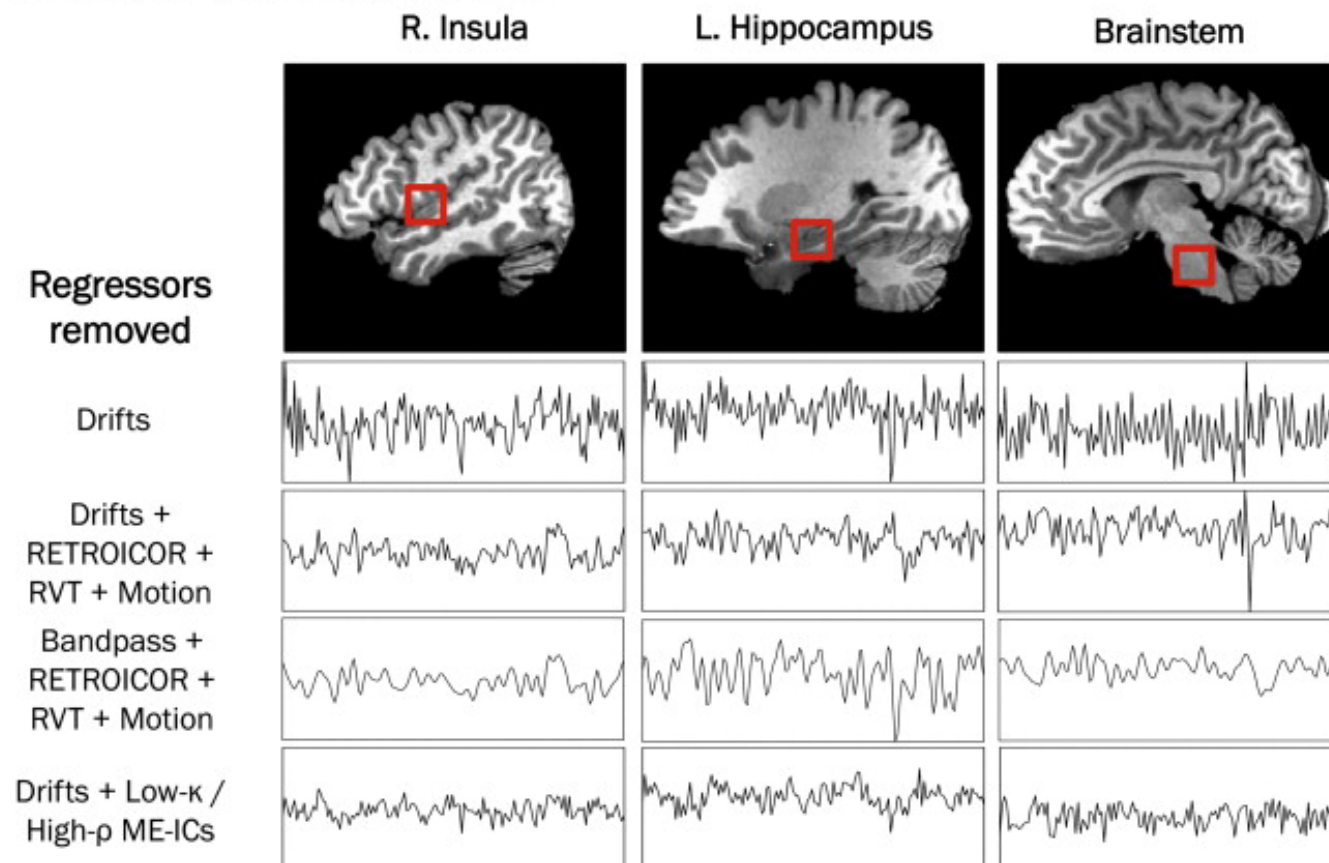
DATA DRIVEN ANALYSIS

If interested in data **driven analysis**, reject low κ components and keep only high κ components above the elbow.

SEED-BASED ANALYSIS

Individual subject denoising for seed-based functional connectivity

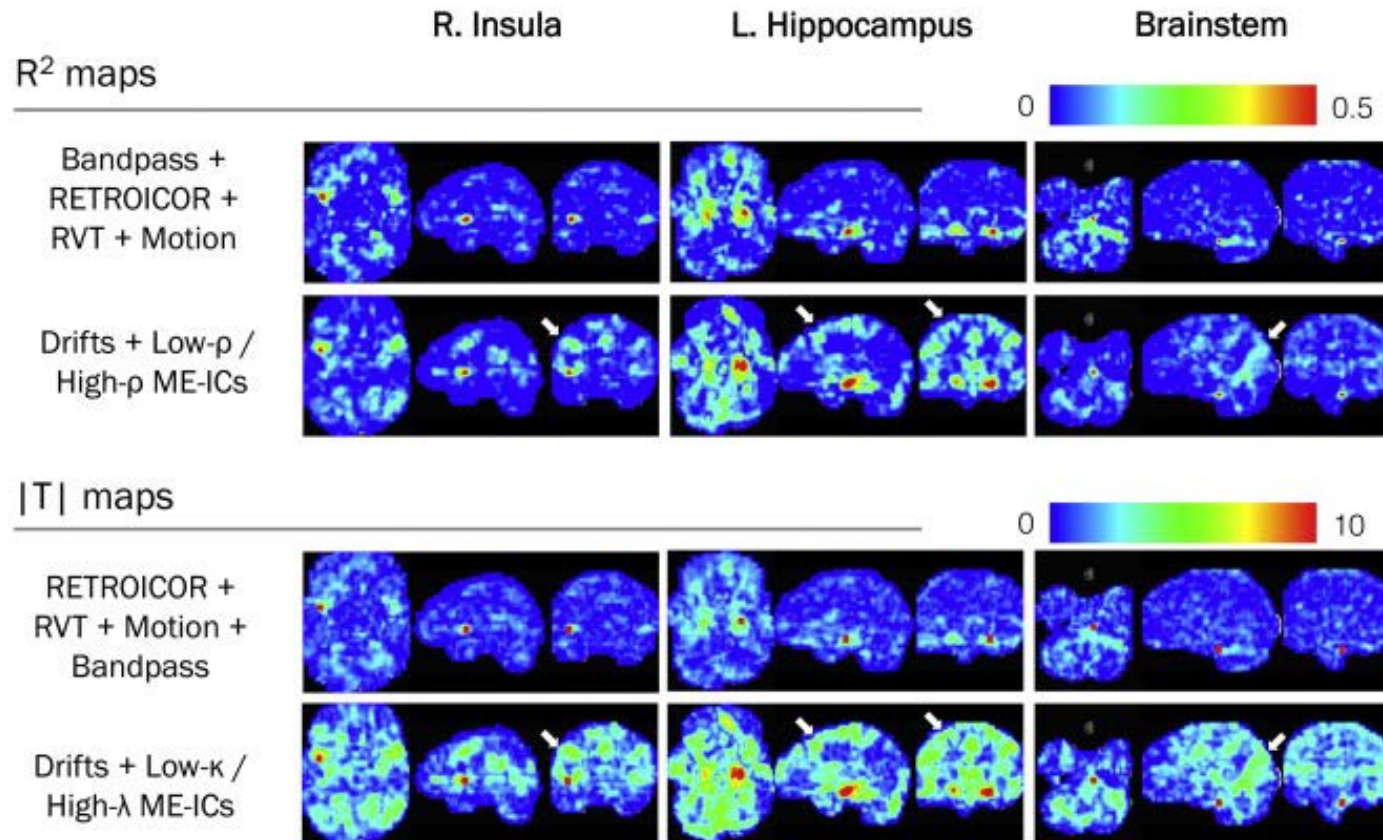
a Denoising effect on seed time courses



If interested in **seed-based connectivity analysis**, then filter out low κ and high ρ components from the data (e.g., as in FIX) prior to analysis.

SEED-BASED ANALYSIS

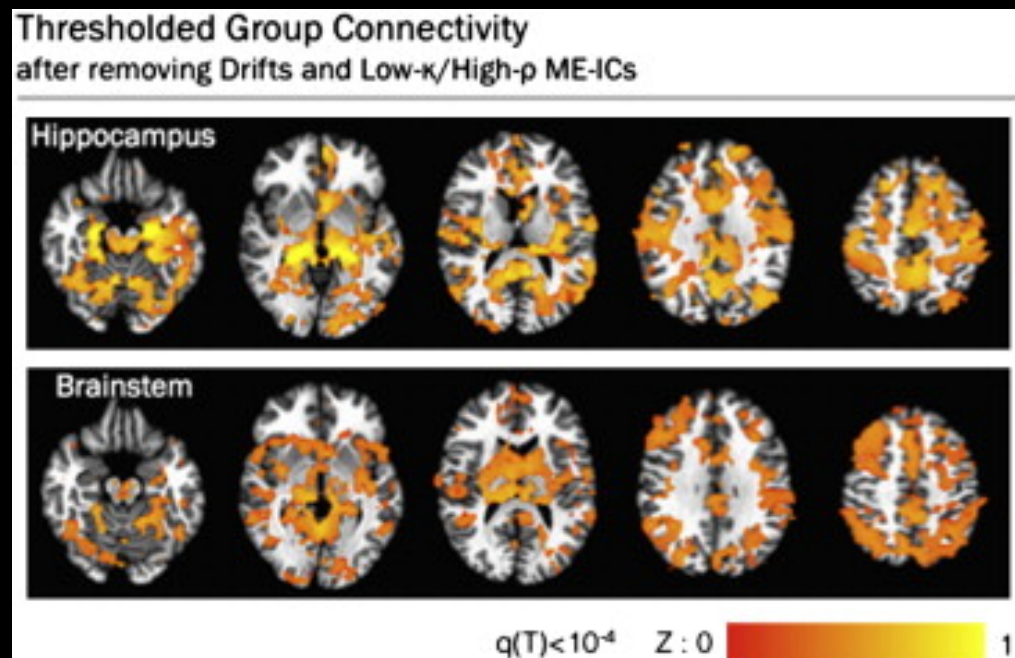
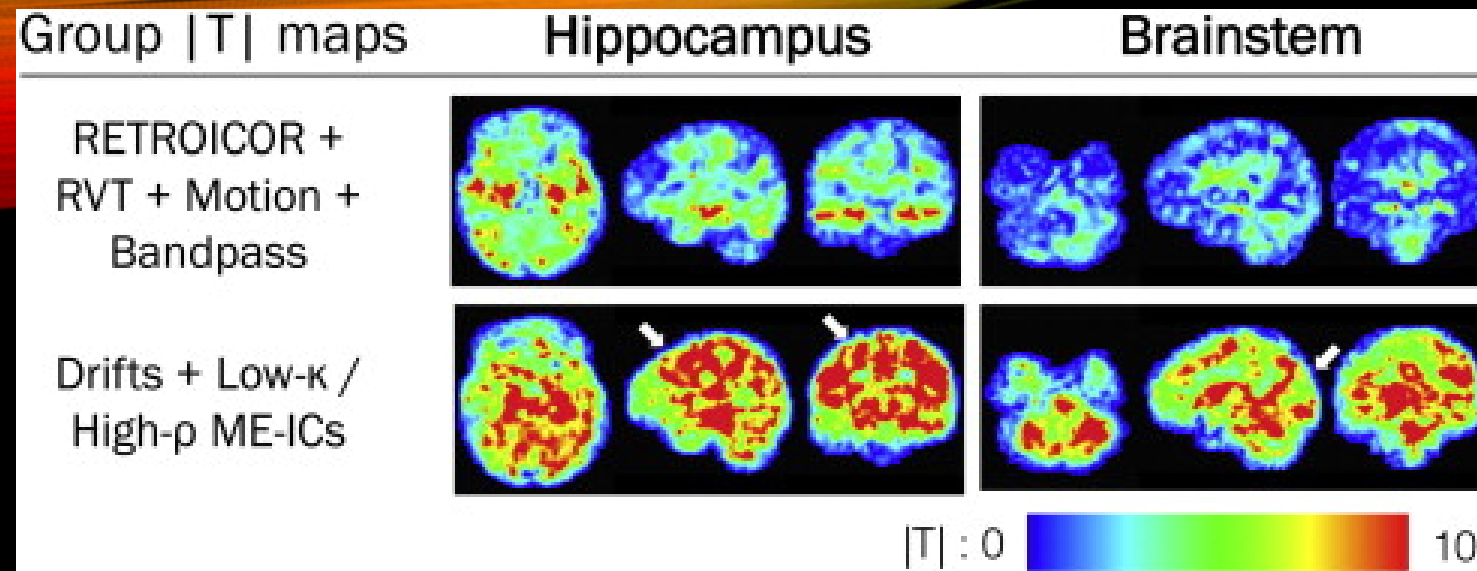
b Denoising effect on functional connectivity maps



If interested in **seed-based connectivity analysis**, then filter out low κ and high ρ components from the data (e.g., as in FIX) prior to analysis.

SEED-BASED ANALYSIS

If interested in **seed-based connectivity analysis**, then filter out low κ and high ρ components from the data (e.g., as in FIX) prior to analysis.



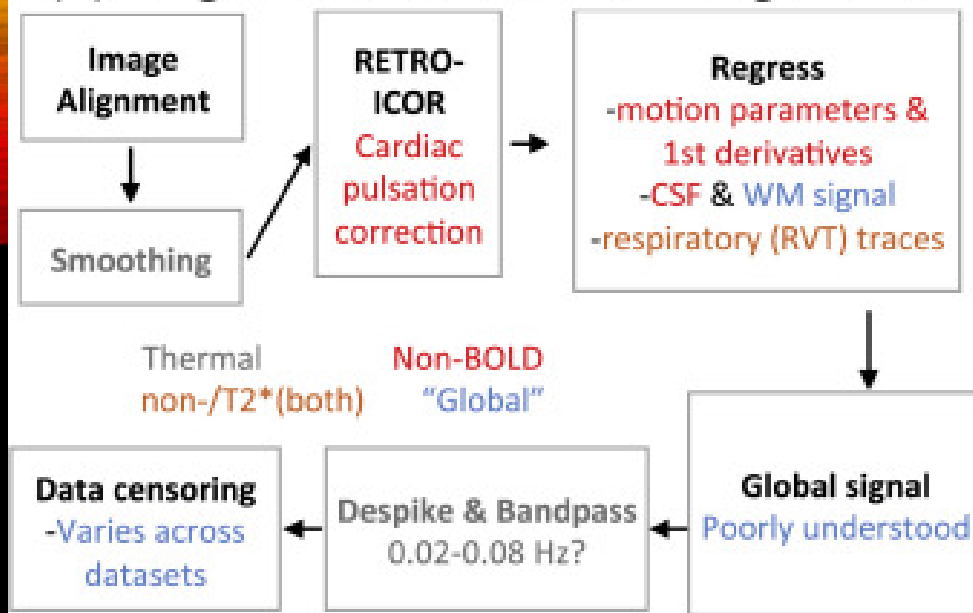
At the same threshold standard approach shows no sig. results

SUMMARIZING

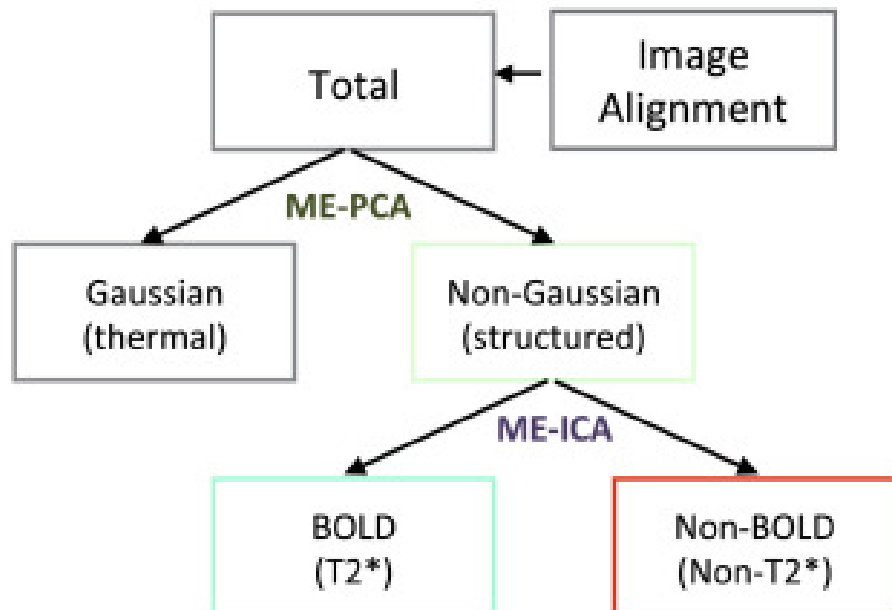
- This technique allows teasing apart data with multi-echo EPI, identifying **BOLD-like** (high κ , low ρ) **non-BOLD-like** (low κ , high ρ) components directly from the data, and using these non BOLD-like components to obtain nuisance regressors.
- PROs:
 - Based on the characteristic properties of BOLD T2* signal (i.e., transverse susceptibility-weighted relaxation rate).
 - Takes advantage of what ICA does best
 - Does not require external physiologic measures, temporal noise models, or anatomical templates
 - Is fully automated
- CONS:
 - Multi-echo data (multi-echo data, multi-echo data)

COMPARING APPROACHES

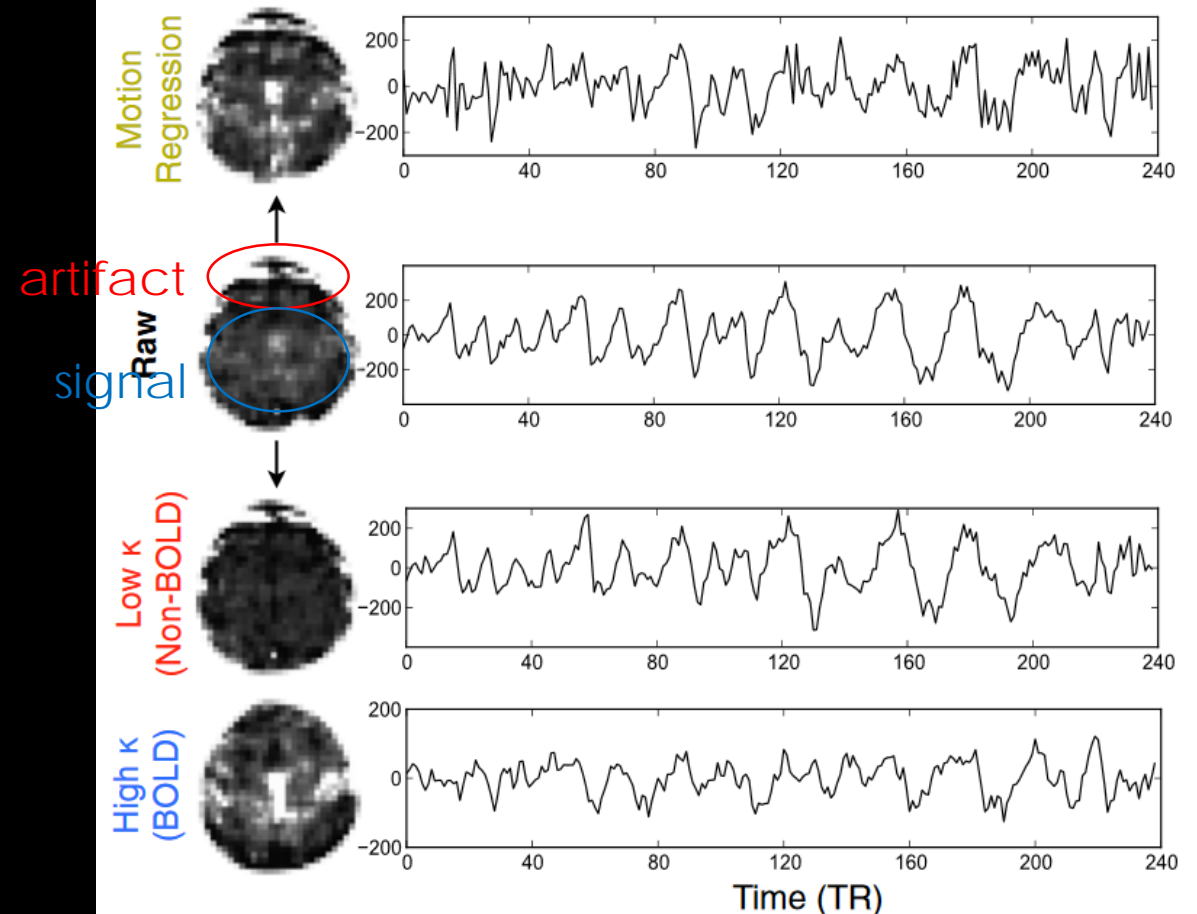
(A) Single-Echo fMRI Processing Model



(B) Multi-Echo fMRI Processing Model

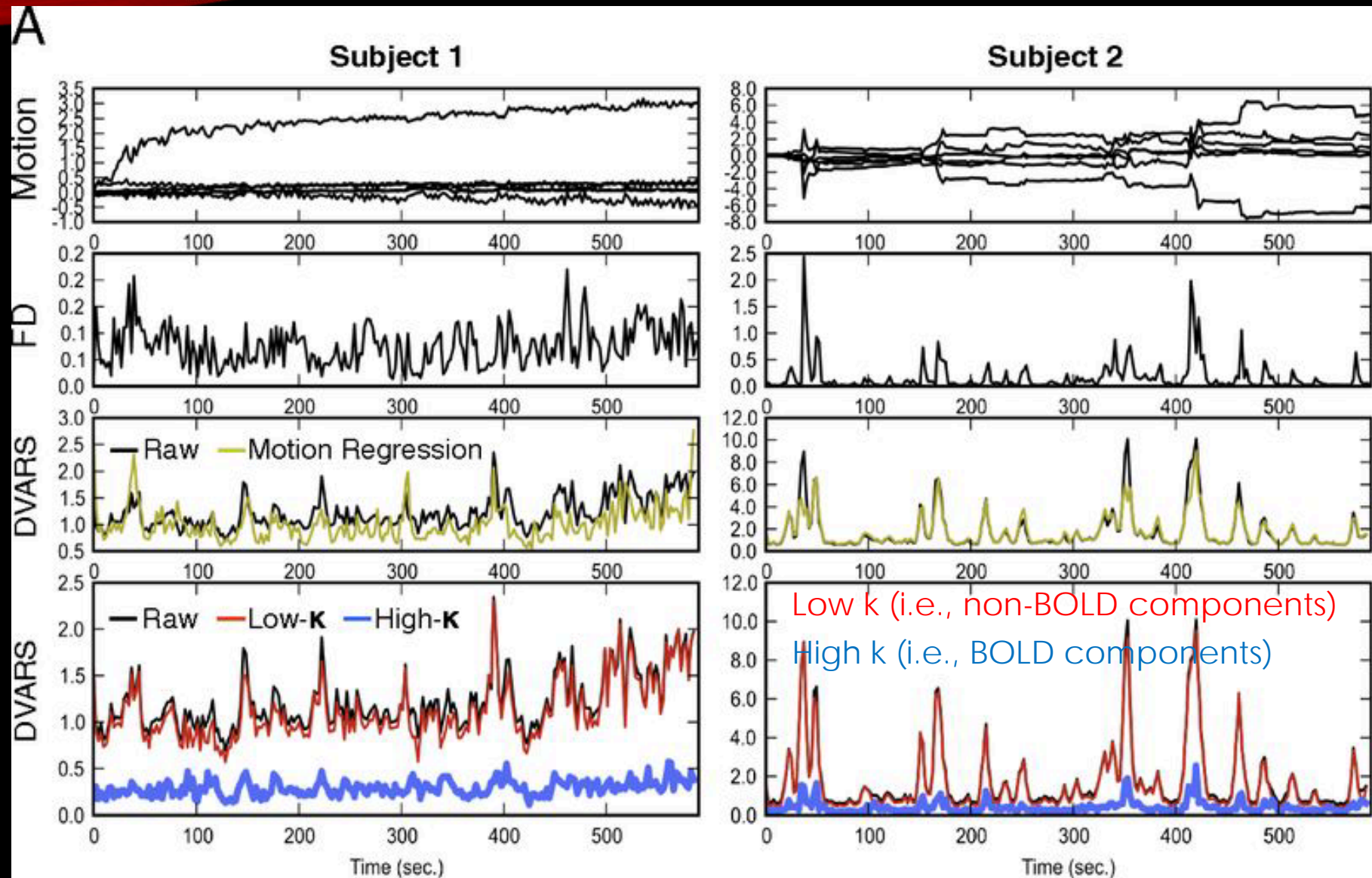


ME-ICA Time Series Denoising



Kundu et al., 2009, PNAS; 2017 NI

ME-ICA AND MOTION



ME-ICA AND TASK-BASED (BLOCK DESIGN) FMRI: MENTALIZING

- Task based approach w/block design
 - Task A: Self/Others (reflective judgments about themselves/HMQ, mentalistic/physical)
 - Task B: Listen to stories (mentalistic/social/physical contents)
- Analyses:
 - ME-ICA denoising
 - Standard approach
 - GLMDenoise (Kay et al 2013)

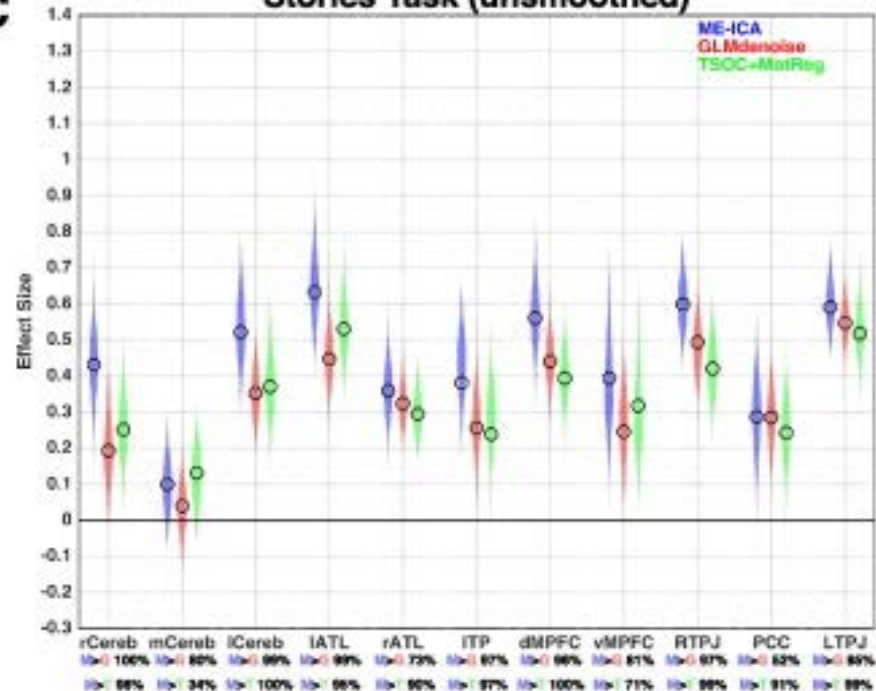
B

SelfOther Task (unsmoothed)



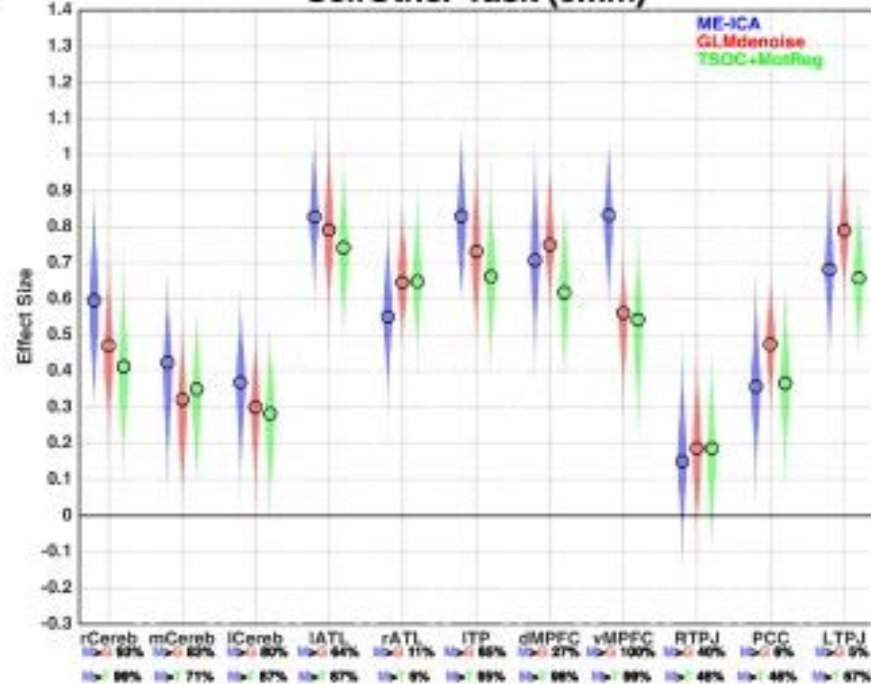
C

Stories Task (unsmoothed)



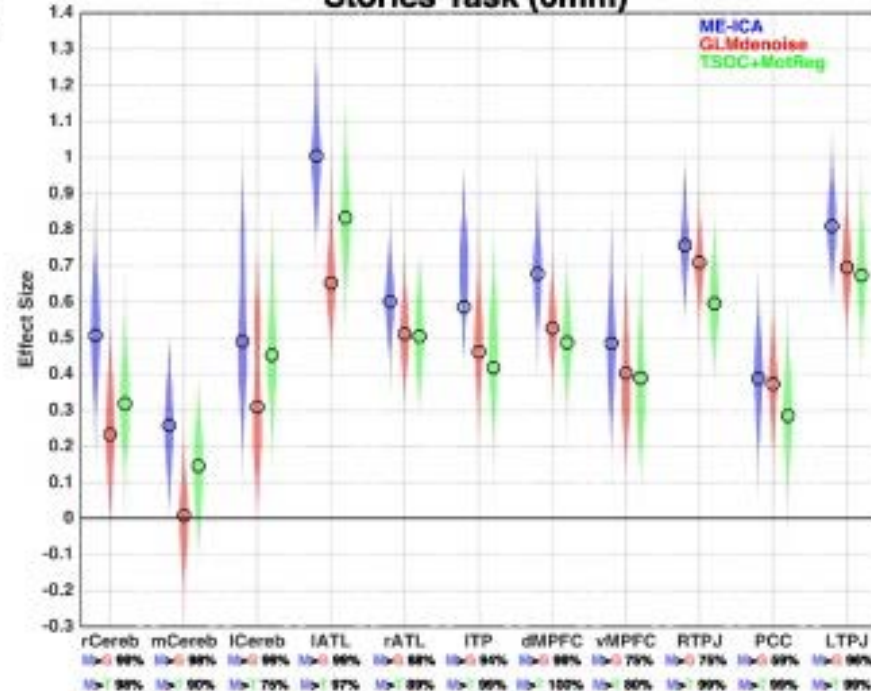
D

SelfOther Task (6mm)

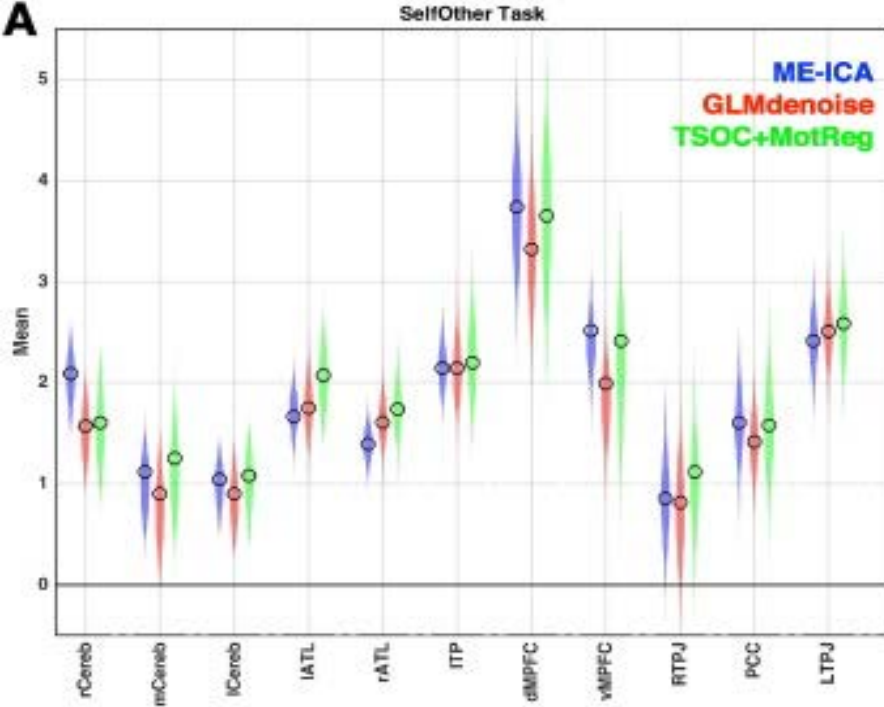
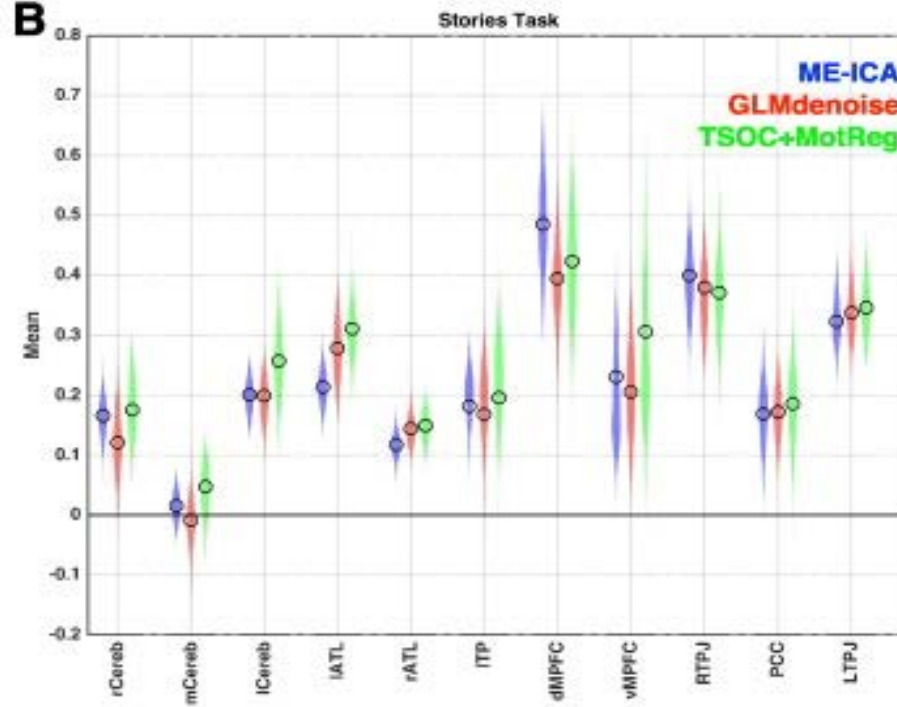
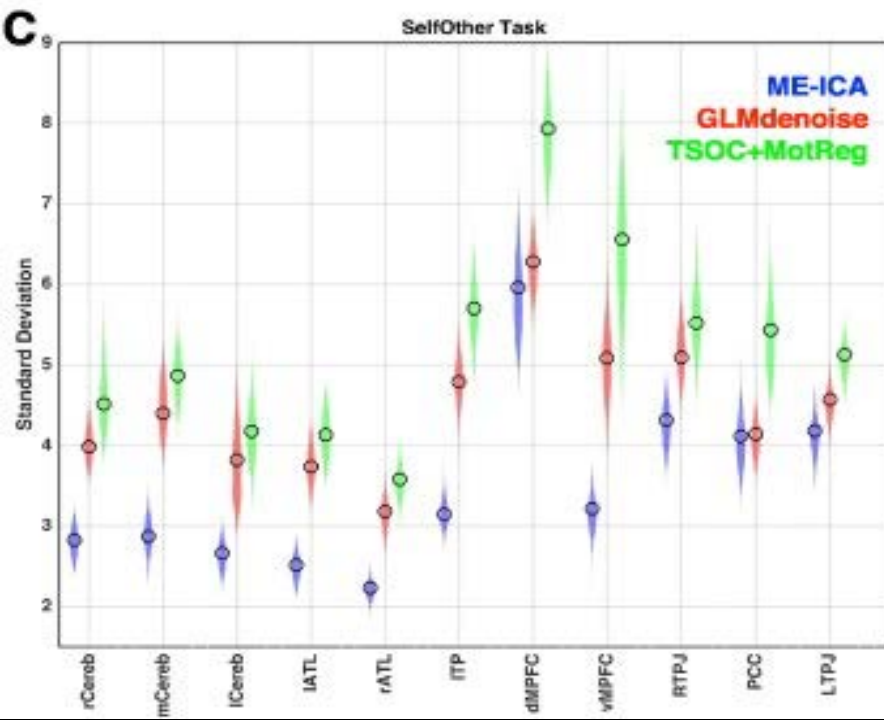
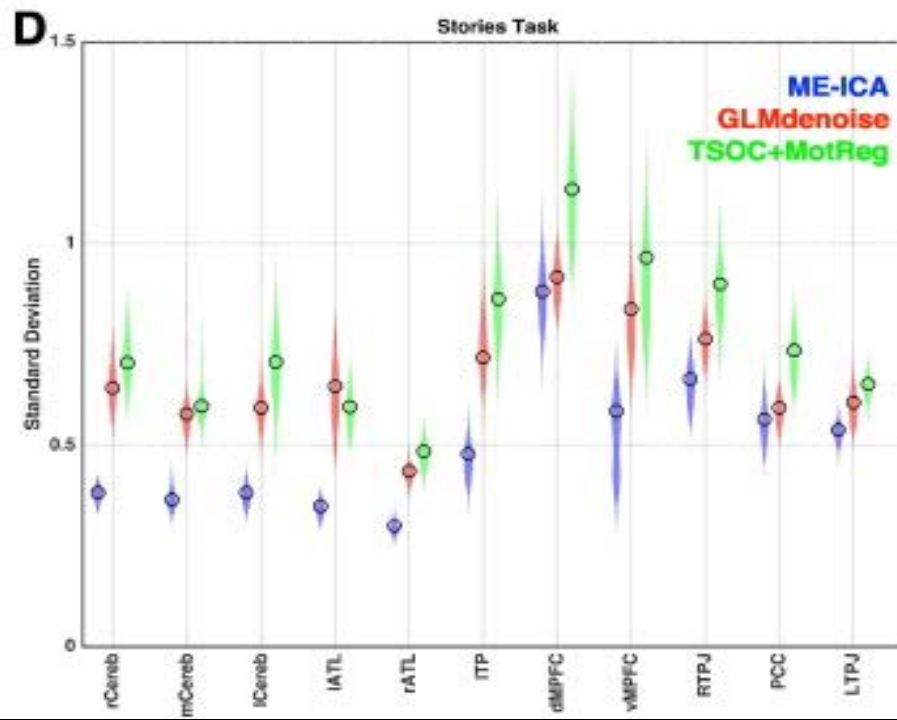


E

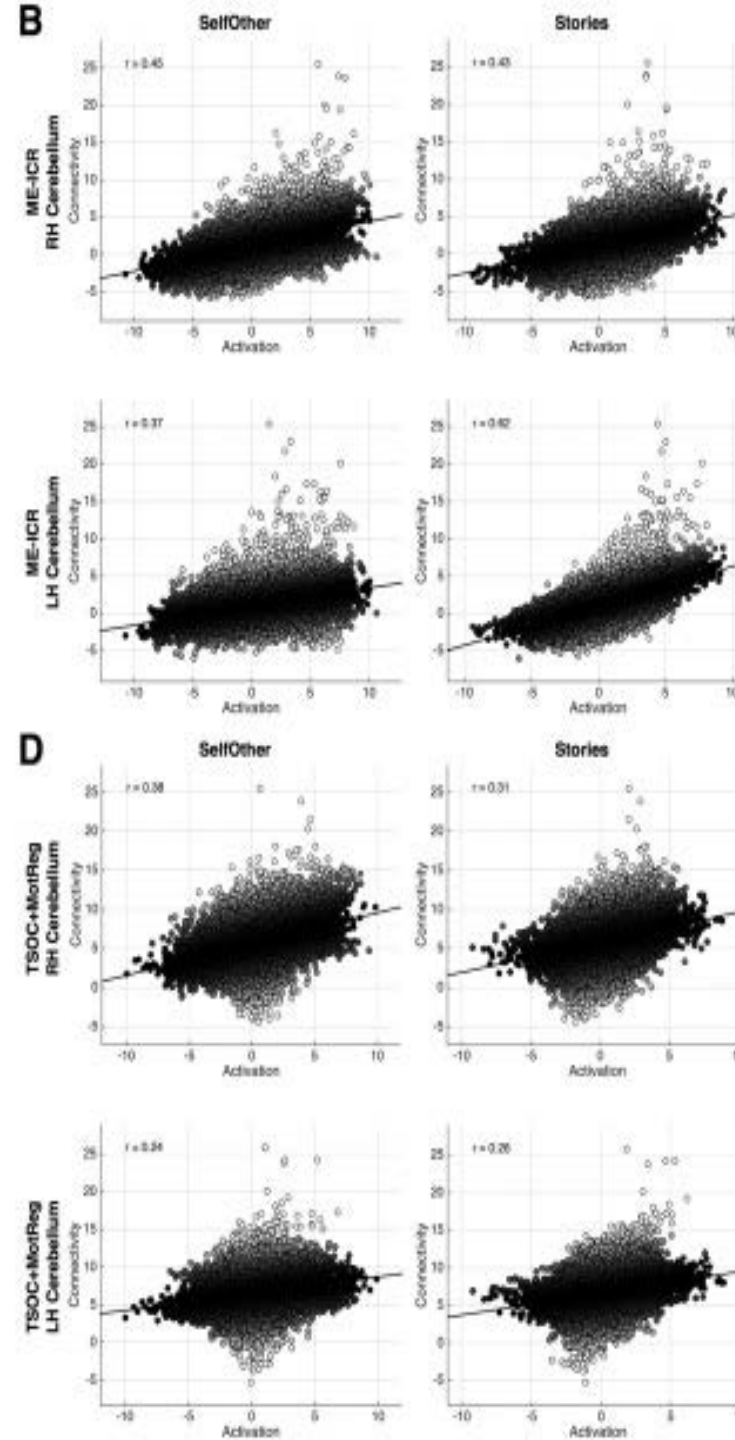
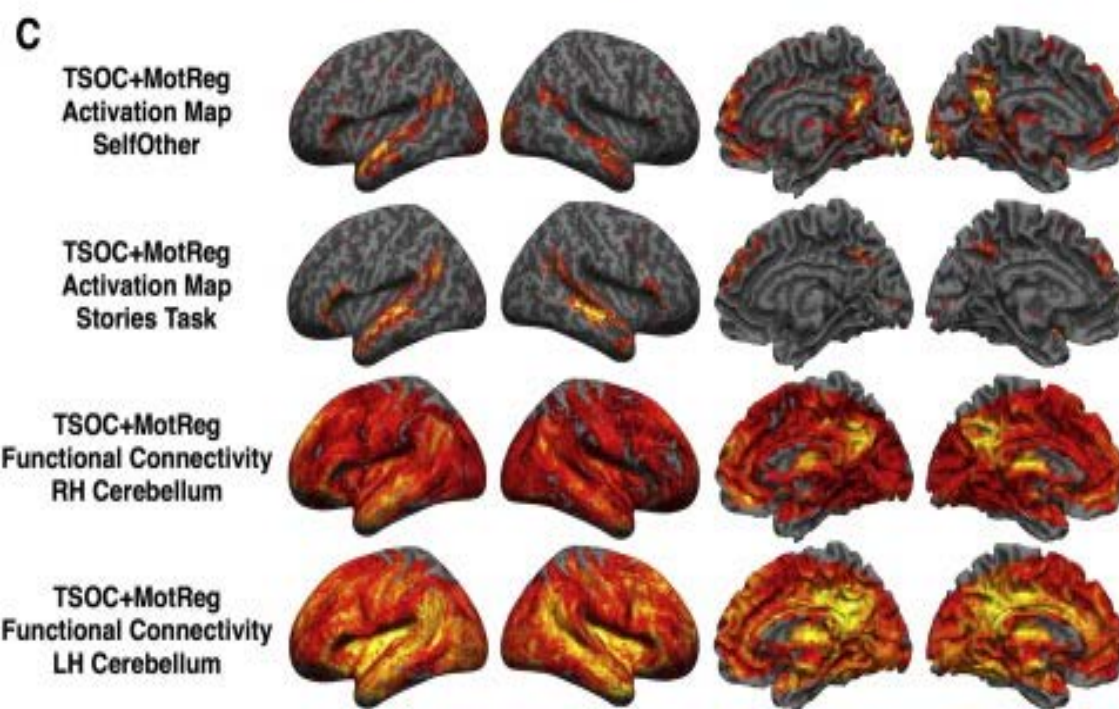
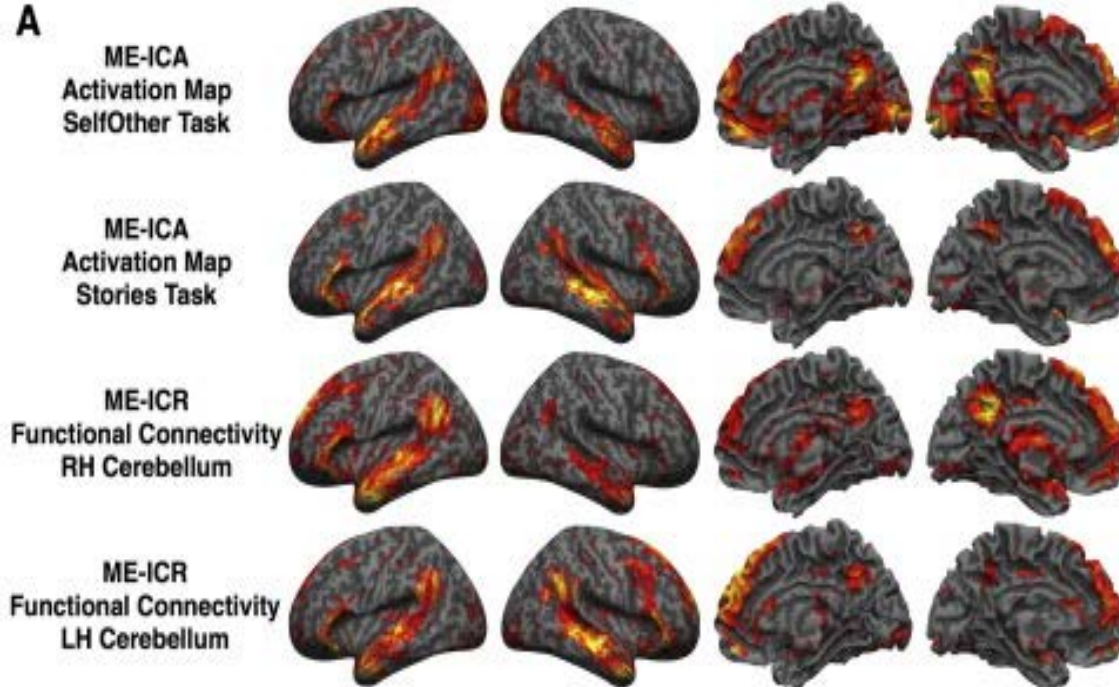
Stories Task (6mm)



ME-ICA AND
TASK-BASED
(BLOCK
DESIGN)
FMRI:
MENTALIZING

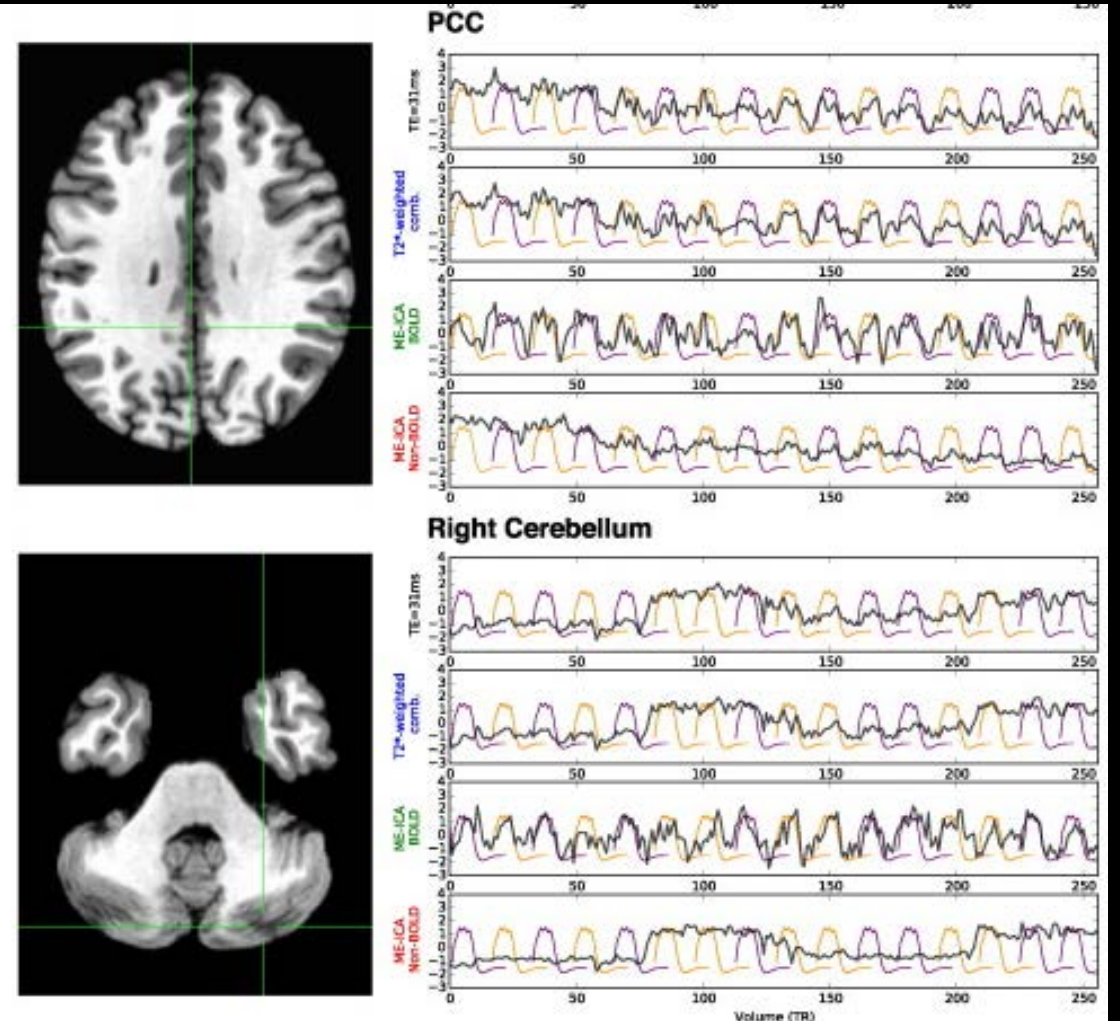
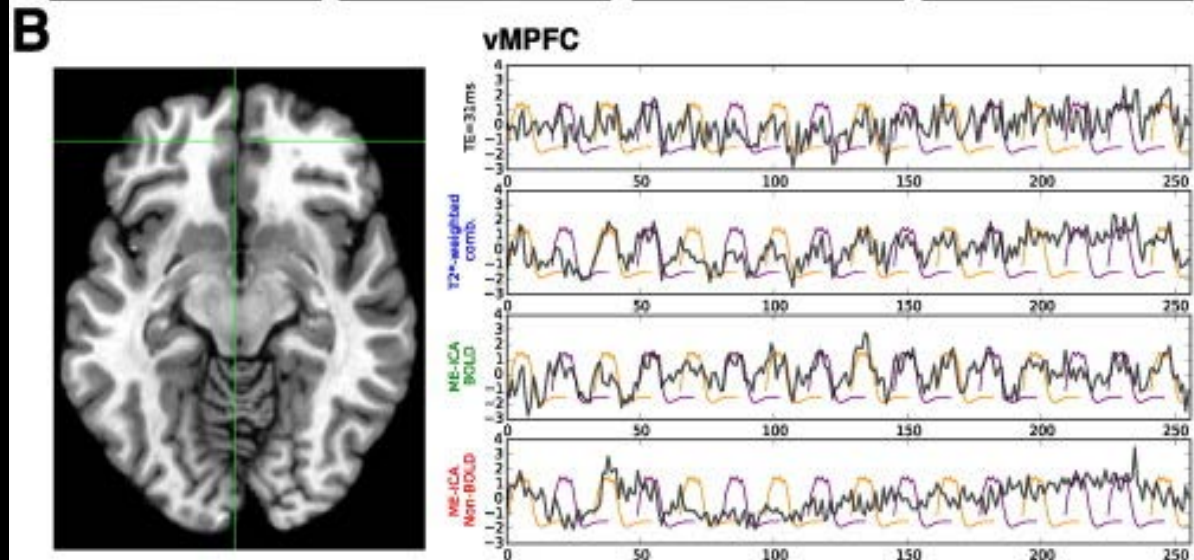
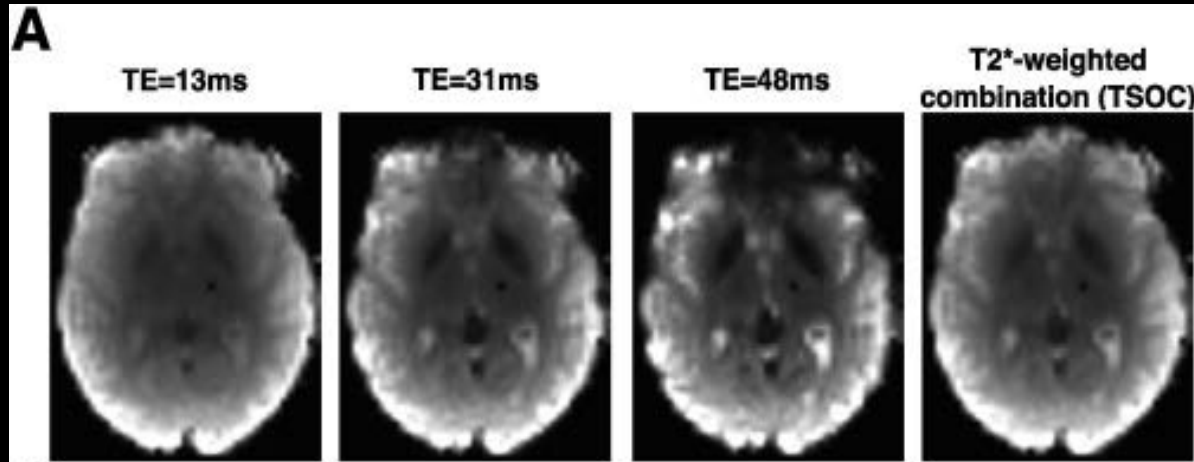
A**B****C****D**

ME-ICA AND
TASK-BASED
(BLOCK
DESIGN)
FMRI:
MENTALIZING



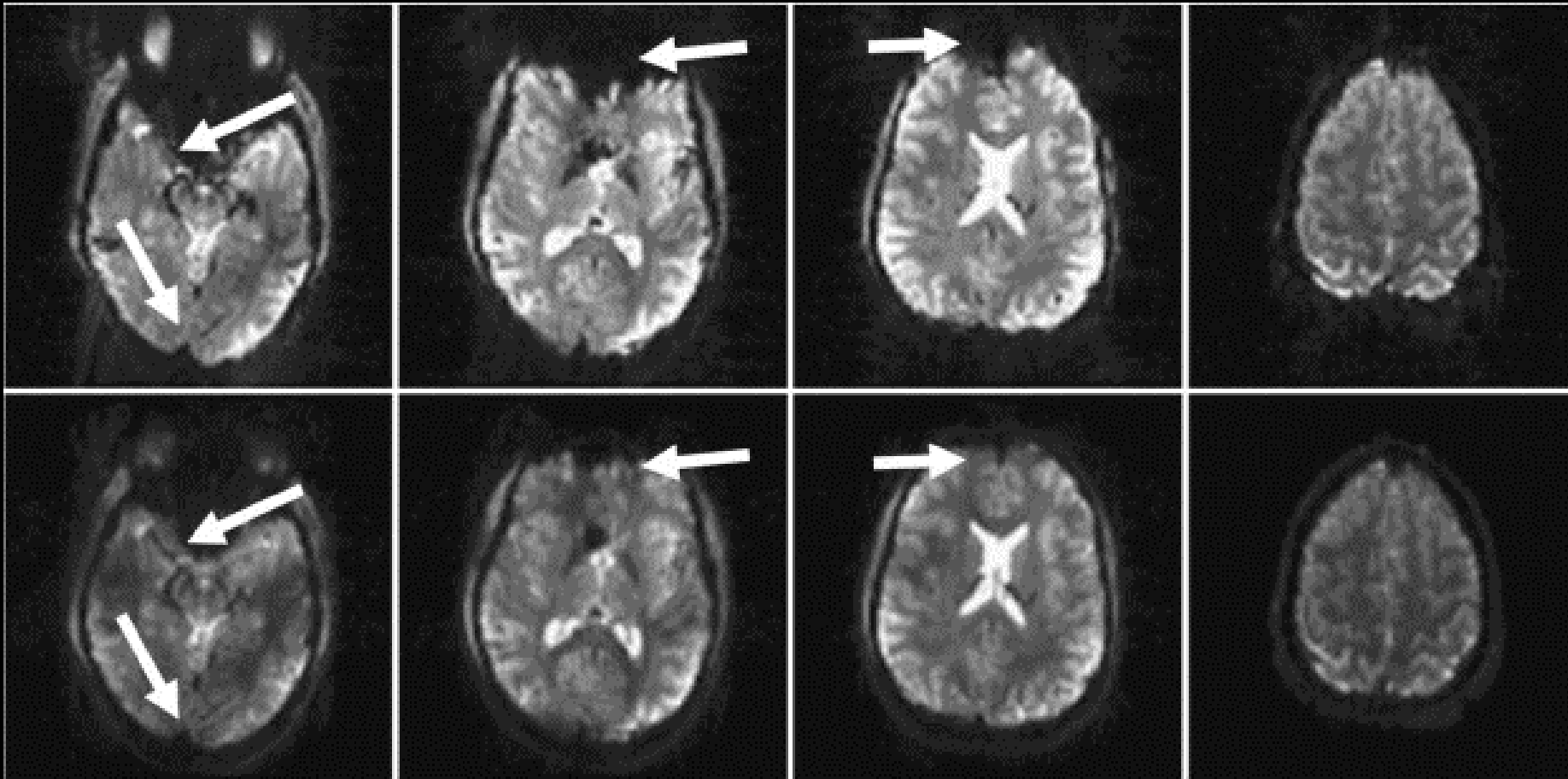
ME-ICA AND TASK-BASED (BLOCK DESIGN) FMRI: MENTALIZING

ME-ICA AND TASK-BASED (BLOCK DESIGN) FMRI: MENTALIZING



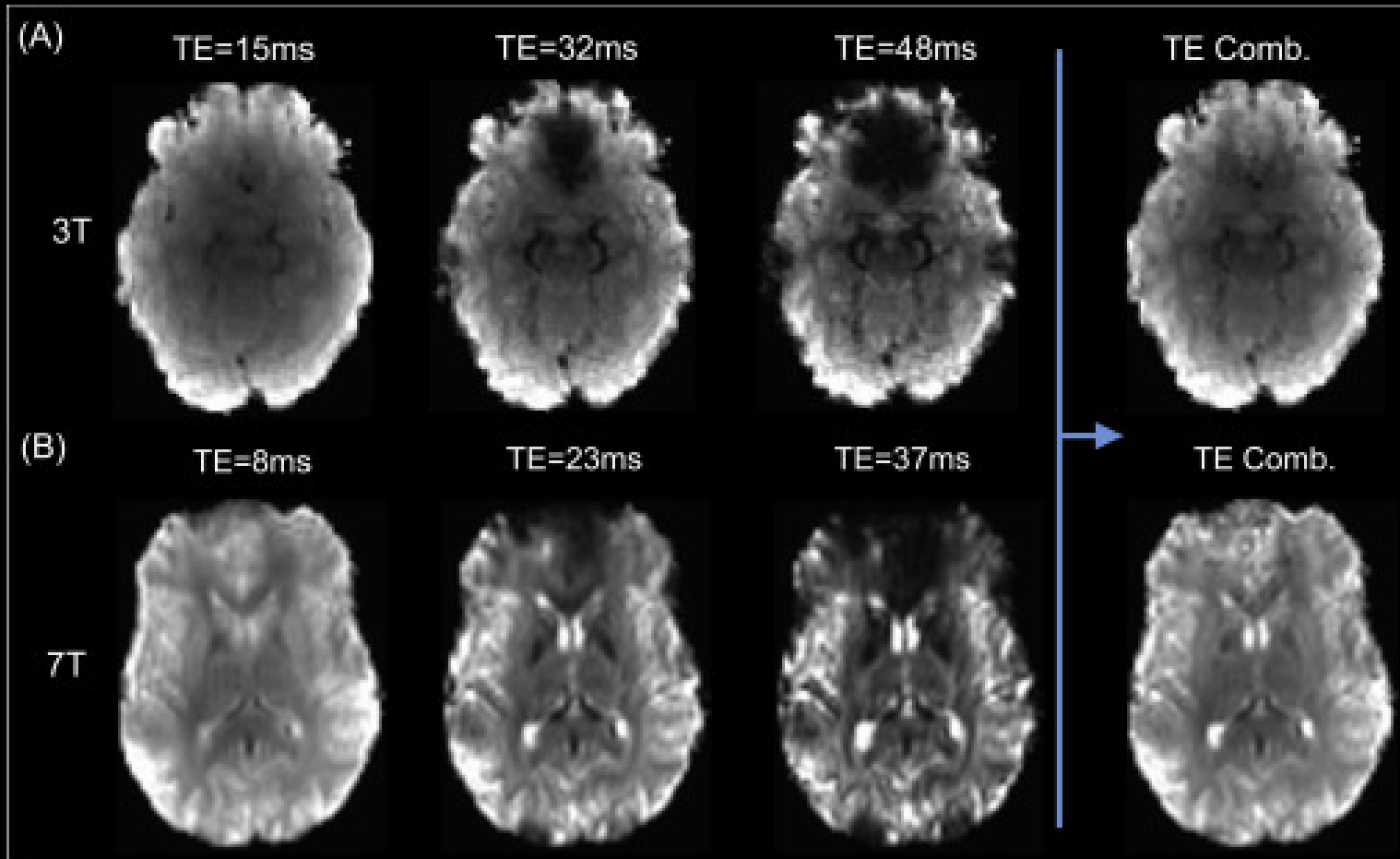
IMPROVING FMRI AT 7T

Conventional single EPI



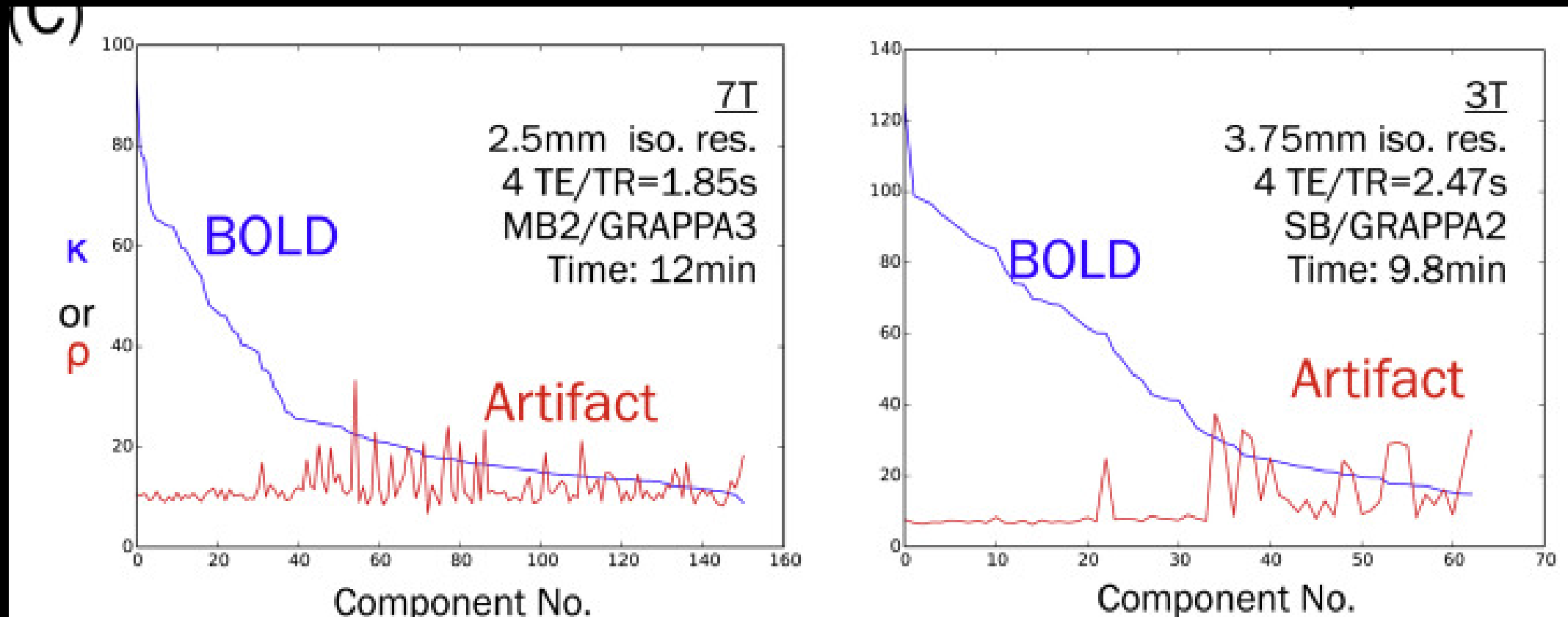
Simple sum of multi-echo EPI

IMPROVING FMRI AT 7T

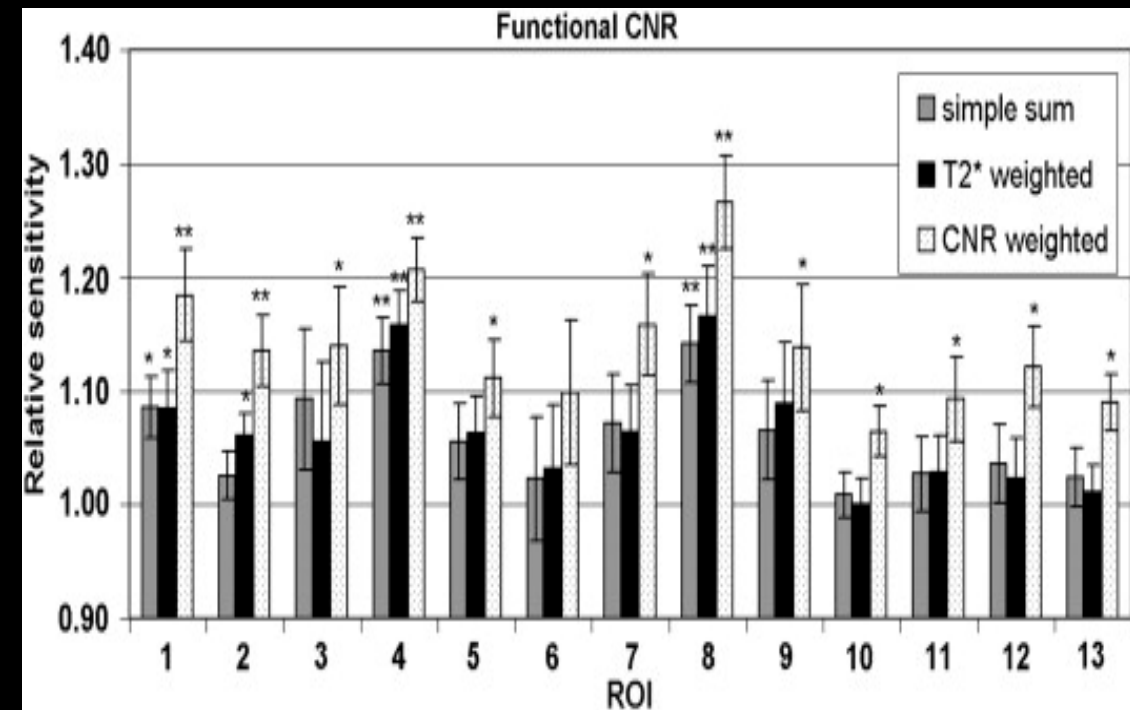
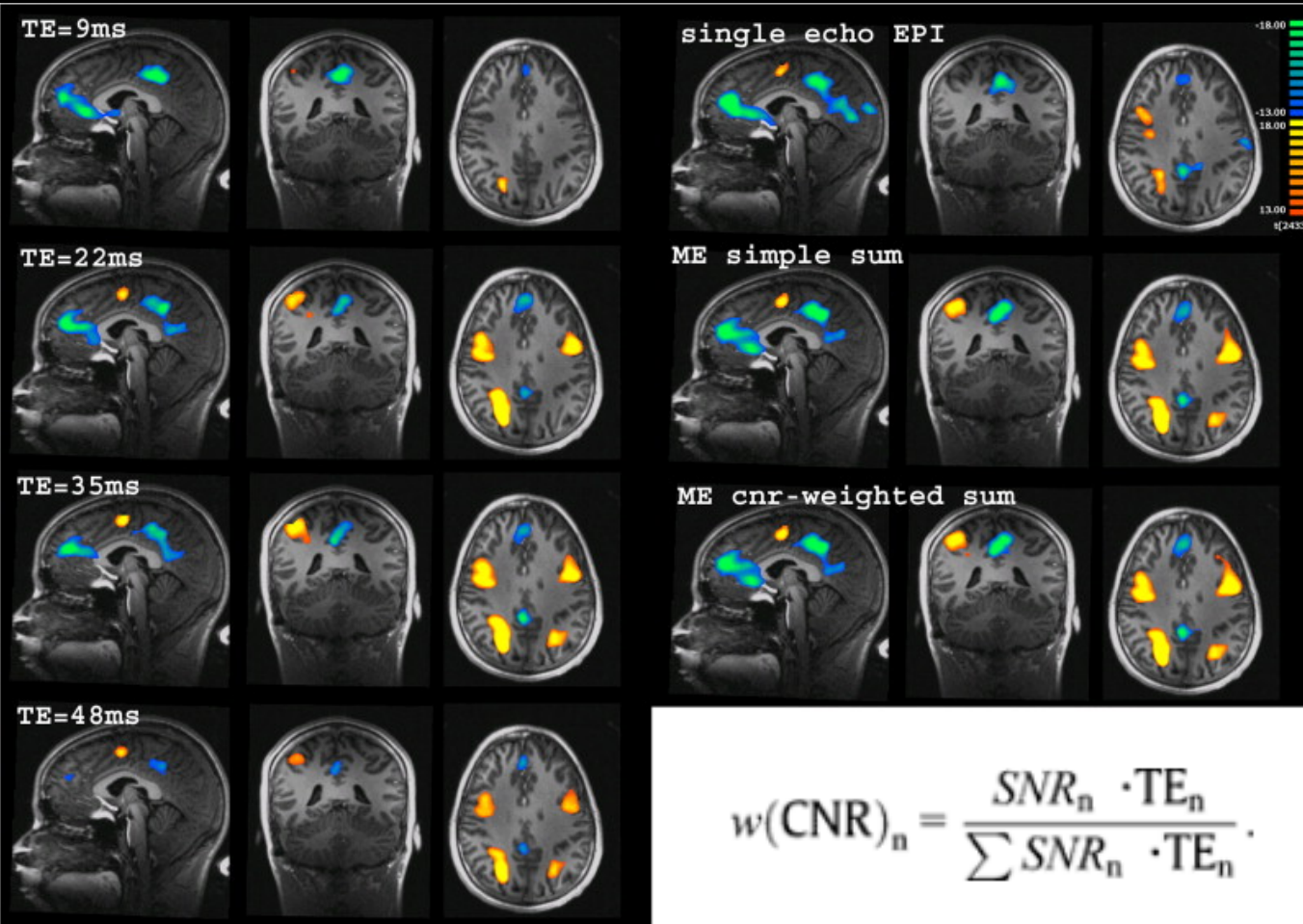


$$w(\text{CNR})_n = \frac{SNR_n \cdot TE_n}{\sum SNR_n \cdot TE_n}.$$

IMPROVING FMRI AT 7T



IMPROVING FMRI AT 7T



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